

Lecture 3: Review of C

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The General Form of a Simple Program

- Simple **C** programs have the form:

directives

```
int main(void)
{
    statements
}
```

- **C** uses { and } in much the same way that some other languages use words like **begin** and **end**.
- Even the simplest **C** programs rely on three key language features:
 - **Directives**
 - **Functions**
 - **Statements**

- Before a **C** program is compiled, it is first edited by a **preprocessor**.
- Commands intended for the **preprocessor** are called **directives**.
- Example:
`#include <stdio.h>`
- `<stdio.h>` is a **header** containing information about **C**'s standard **I/O** library.
- Directives always begin with a **#** character.
- By default, directives are one line long; there's no semicolon or other special marker at the end.

- Our standard directive will be the following:
#include “stm321476xx.h”
- The **stm321476xx.h** file contains:
 - Data structures and the address mapping for all peripherals.
 - Peripheral's registers declarations and bits definition.
 - Macros to access peripheral's registers hardware.
- Example:

```
/****** Bit definition for RCC_AHB2ENR register *****/  
  
#define  RCC_AHB2ENR_GPIOAEN      ((uint32_t)0x00000001U)  
#define  RCC_AHB2ENR_GPIOBEN      ((uint32_t)0x00000002U)  
#define  RCC_AHB2ENR_GPIOCEN      ((uint32_t)0x00000004U)  
#define  RCC_AHB2ENR_GPIODEN      ((uint32_t)0x00000008U)  
#define  RCC_AHB2ENR_GPIOEEN      ((uint32_t)0x00000010U)  
#define  RCC_AHB2ENR_GPIOFEN      ((uint32_t)0x00000020U)  
#define  RCC_AHB2ENR_GPIOGEN      ((uint32_t)0x00000040U)  
#define  RCC_AHB2ENR_GPIOHEN      ((uint32_t)0x00000080U)  
#define  RCC_AHB2ENR_OTGFSEN      ((uint32_t)0x00001000U)  
#define  RCC_AHB2ENR_ADCEN        ((uint32_t)0x00002000U)  
#define  RCC_AHB2ENR_RNGEN        ((uint32_t)0x00040000U)
```

- A **function** is a series of statements that have been grouped together and given a name.
- **Library functions** are provided as part of the **C** implementation.
- A function that computes a value uses a **return** statement to specify what value it “returns”:

```
return x + 1;
```



The `main` Function

- The `main` function is mandatory.
- `main` is special: it gets called automatically when the program is executed.
- `main` returns a status code; the value 0 indicates normal program termination.
- If there's no `return` statement at the end of the `main` function, many compilers will produce a warning message.
 - The compiler used in our labs does not requires a `return` statement at the end of the `main` function.

- A **statement** is a command to be executed when the program runs.
- Asking a function to perform its assigned task is known as **calling** the function.
- For example, to display a string we call the **printf** function:
`printf("To C, or not to C: that is the question.\n");`

- When the **printf** function displays a **string literal** - characters enclosed in double quotation marks - it doesn't show the quotation marks.
- **printf** doesn't automatically advance to the next output line when it finishes printing.
- To make **printf** advance one line, include `\n` (the *new-Line character*) in the string to be printed.
- However, when programming at the Bare Metal Layer, we do not have access to the **printf** function.
- When developing for embedded systems, debugging is done by manually verifying the values of the processor registers.

- A **comment** begins with **/*** and end with ***/**.
/* This is a comment */
- A single line comment can be written using **//**. For example:
// This is a single line comment
- Comments may appear almost anywhere in a program, either on separate lines or on the same lines as other program text.
- Comments may extend over more than one line.
**/* Name: pun.c
Purpose: Prints a bad pun.
Author: K. N. King */**

Overall Program Structure

```
#include "stm32l476xx.h"
```

This **directive** will always be used in all our programs!

```
int main(void){
```

Always use **int main(void)**!

```
RCC->AHB2ENR |= 0x02; // Enable clock of Port B
```

```
GPIOB->MODER &= ~(3<<4); // Clear mode bits
```

```
GPIOB->MODER |= 1<<4; // Set mode to output
```

```
GPIOB->OTYPER &= ~(1<<2); // Select push-pull output
```

```
GPIOB->ODR |= 1 << 2; // Output 1 to turn on red LED
```

```
while(1) {  
}
```

All of your programming logic goes inside this dead loop.

The red lines are the **statements** of this program.

Remember: when modifying registers, always use **bitwise operations**!

Indentation is important to keep your code organized. We normally use a single Tab or four Spaces.

Comments



Variables and Assignment

- Most programs need a way to store data temporarily during program execution.
 - Our brain does this as well to remember key events in our life!
 - Or, perhaps, our phone number or home address.
- These storage locations are called **variables**.
- **Variables** must be **declared** before they are used.

Variable Types

- Every variable must have a **type**.
- **C** has a wide variety of types, including **int** and **float**.
- A variable of type **int** (short for *integer*) can store a whole number such as **0**, **1**, **392**, or **-2553**.
 - The largest **int** value is typically **2,147,483,647** but can be as small as **32,767**.
- A variable of type **float** (short for *floating-point*) can store much larger numbers than an **int** variable.
- Also, a **float** variable can store numbers with digits after the decimal point, like **379.125**.
- Drawbacks of **float** variables:
 - Slower arithmetic
 - Approximate nature of **float** values

Variable Types

- Variables can be declared one at a time:
`int height;`
`float profit;`
- Alternatively, several can be declared at the same time:
`int height, length, width, volume;`
`float profit, loss;`

Variable Types

- When dealing with the **32-bit registers** in our **ARM Cortex-M4** processor, we are going to use a special variable type called **fixed width integer types**.
- These are the most common ones we are going to be using:
 - **uint8_t**
 - **uint16_t**
 - **uint32_t**
 - **uint64_t**
- These represent **unsigned integer type** with *width of exactly* **8, 16, 32 and 64 bits**, respectively.

Variable Types

- When **main** contains **declarations**, these must precede **statements**:

```
int main(void)
{
    declarations
    statements
}
```

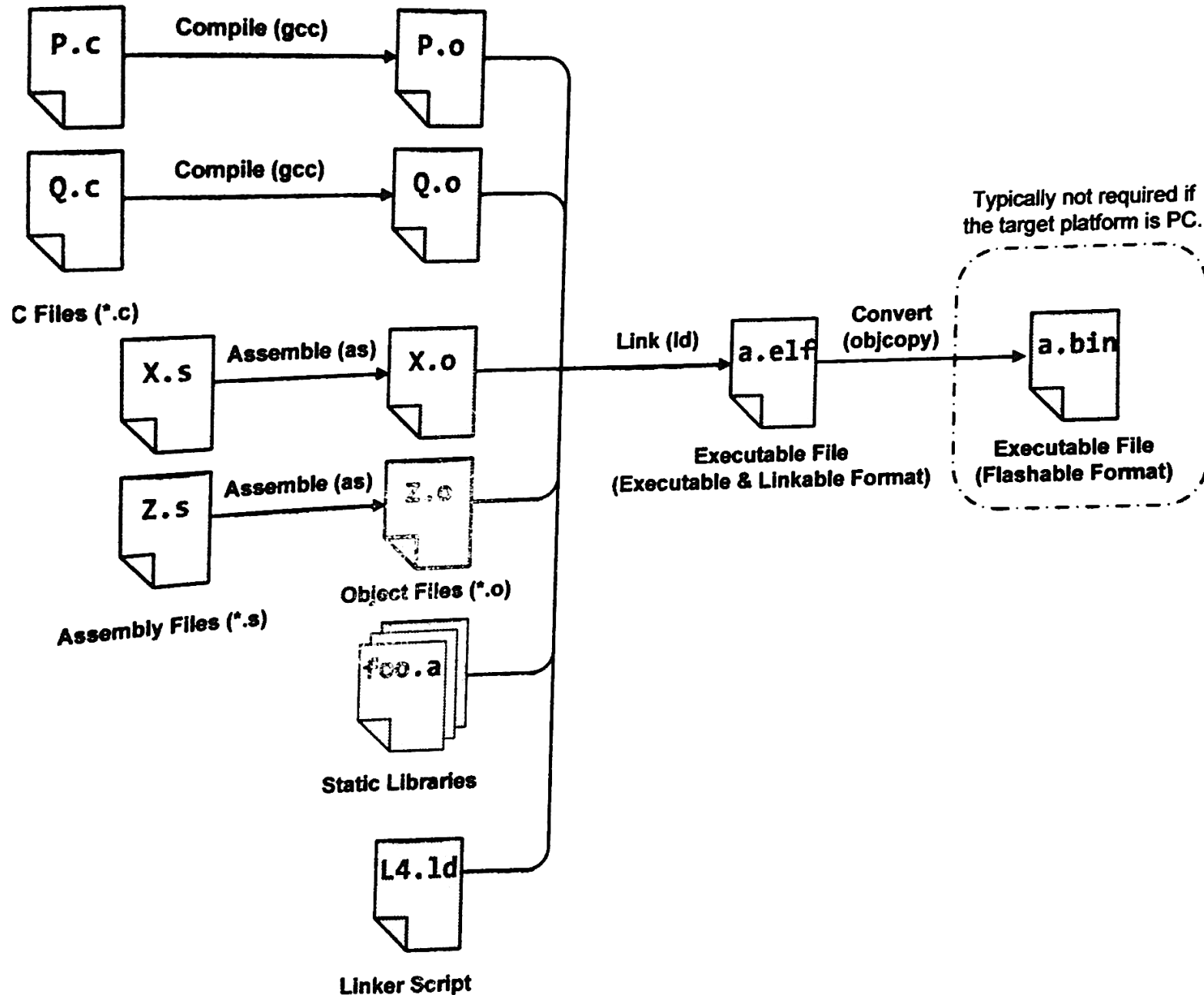
Defining Names for Constants

- If you are writing a program that use the same constant number throughout your code, you can use a feature called **macro definition**.
- For example:
#define RED_LED_PIN 2
- The above line will make the name **RED_LED_PIN** equal to the numeral **2**.
- When a program is compiled, the **preprocessor** replaces each **macro** by the value that it represents.
- The value of a macro can be an expression:
#define RECIPROCAL_OF_PI (1.0f / 3.14159f)
- If it contains operators, the expression should be enclosed in parentheses.
- Using only upper-case letters in macro names is a common convention.

- The **GNU Compiler Collection (GCC)** consists of a suite of free, open-source, and widely used programming and debugging tools for many types of processors, such as x86/x64, ARM, MIPS, and AVR. The following lists a few important tools.
 - The **GNU C compiler (gcc)** translates a **C** source file to an assembly file or to an object file (machine code).
 - The **assembler (as)** converts an assembly program to an object file.
 - The **linker (ld)** links object files and pre-compiled libraries into an executable file in a format such as **ELF (Executable and Linkable Format)**.

- To program microprocessors, flash programmers often require us to convert the **ELF** format to a specific binary format that can be directly written to **flash** or **ROM**. We can use **objcopy** to achieve the conversion.
- The **debugger** (**gdb**) allow us to debug a program step by step.

GNU Compiler



- Commands to build the project given in the previous slide:

```
gcc -c -g -o P.o P.c
```

```
gcc -c -g -o Q.o Q.c
```

```
as -g -o X.o X.s
```

```
as -g -o X.o X.s
```

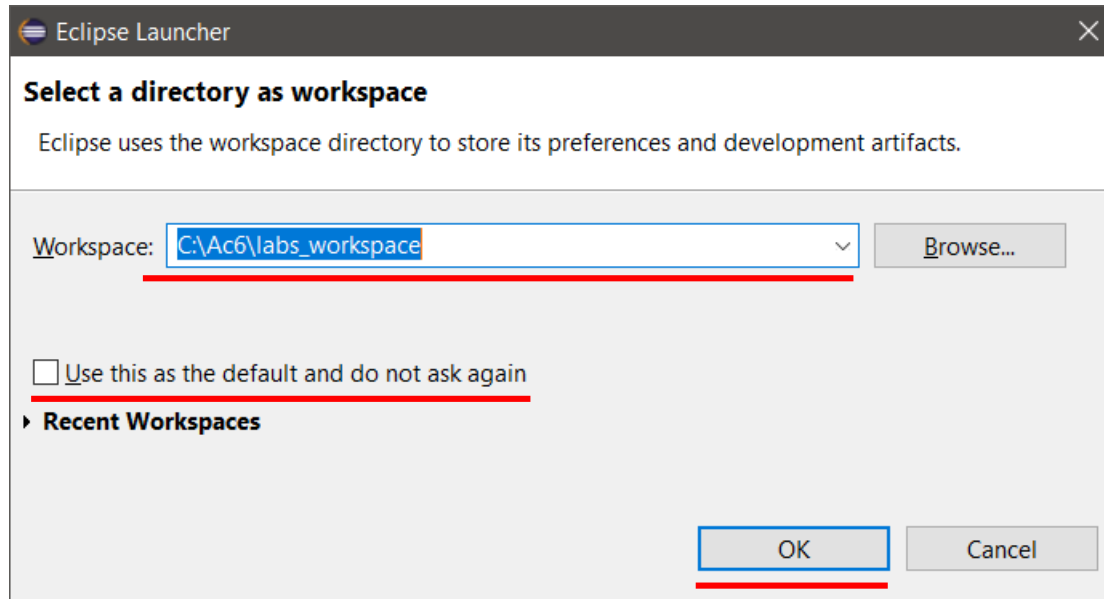
```
as -g -o Z.o Z.s
```

```
ld TL4.ld -lfoo -o a.elf P.o Q.o X.o Q.o
```

```
objcopy -O binary a.elf a.bin
```

Creating a New Project on System Workbench

- The first time you open the System Workbench IDE, you will have to select a folder where all your projects will be located.



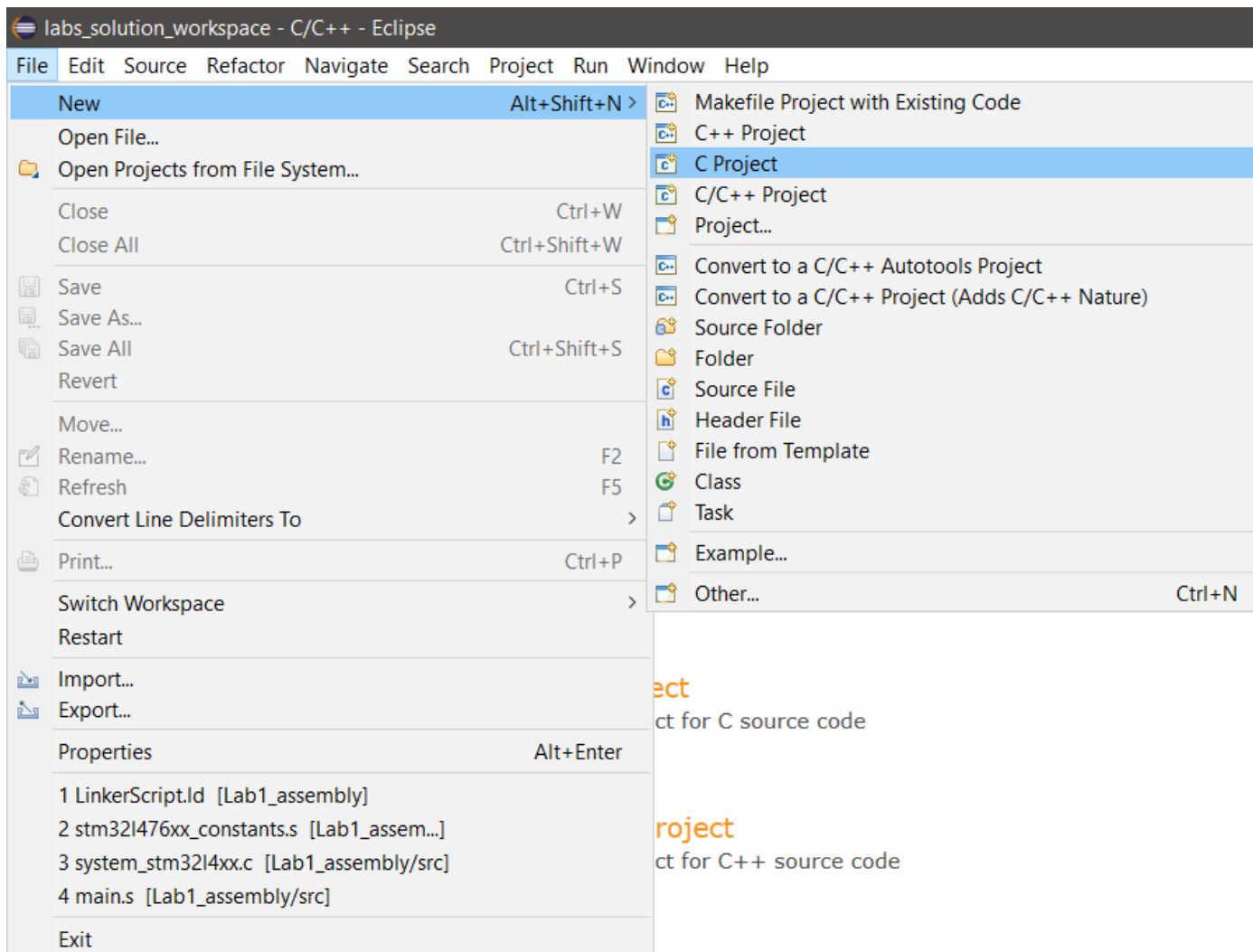
Important: Your workspace folder CANNOT contain any spaces in its name! Otherwise, you will face compilation errors.

It is recommended to create a folder in your **C:** unit.

- If you don't want to always the folder every time you open the IDE, you can check the box **Use this as the default and do not ask again.**
- Click on the OK button to open the IDE.

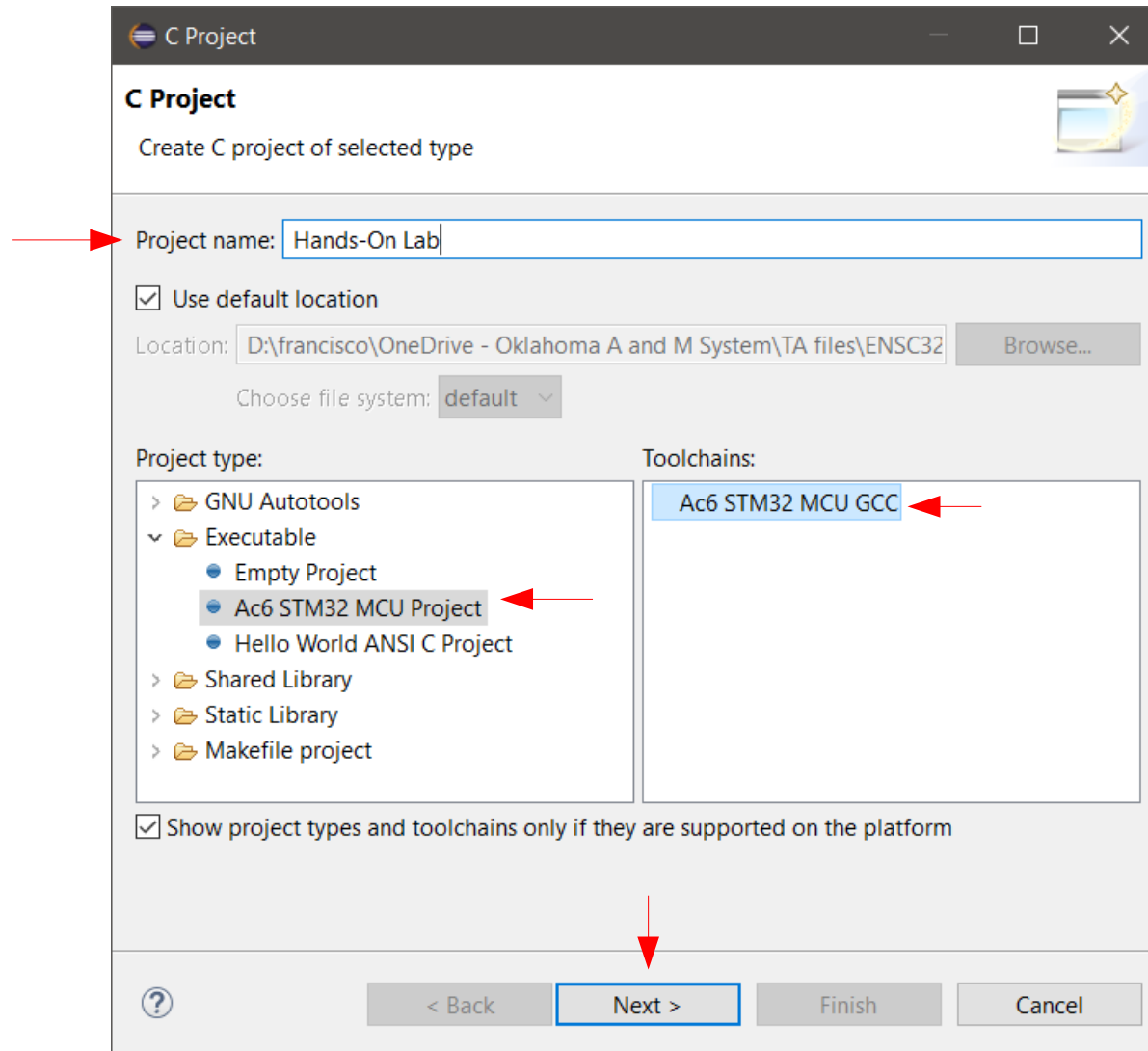
Creating a New Project on System Workbench

- Once the IDE has opened, you need to select **File** → **New** → **C Project**.



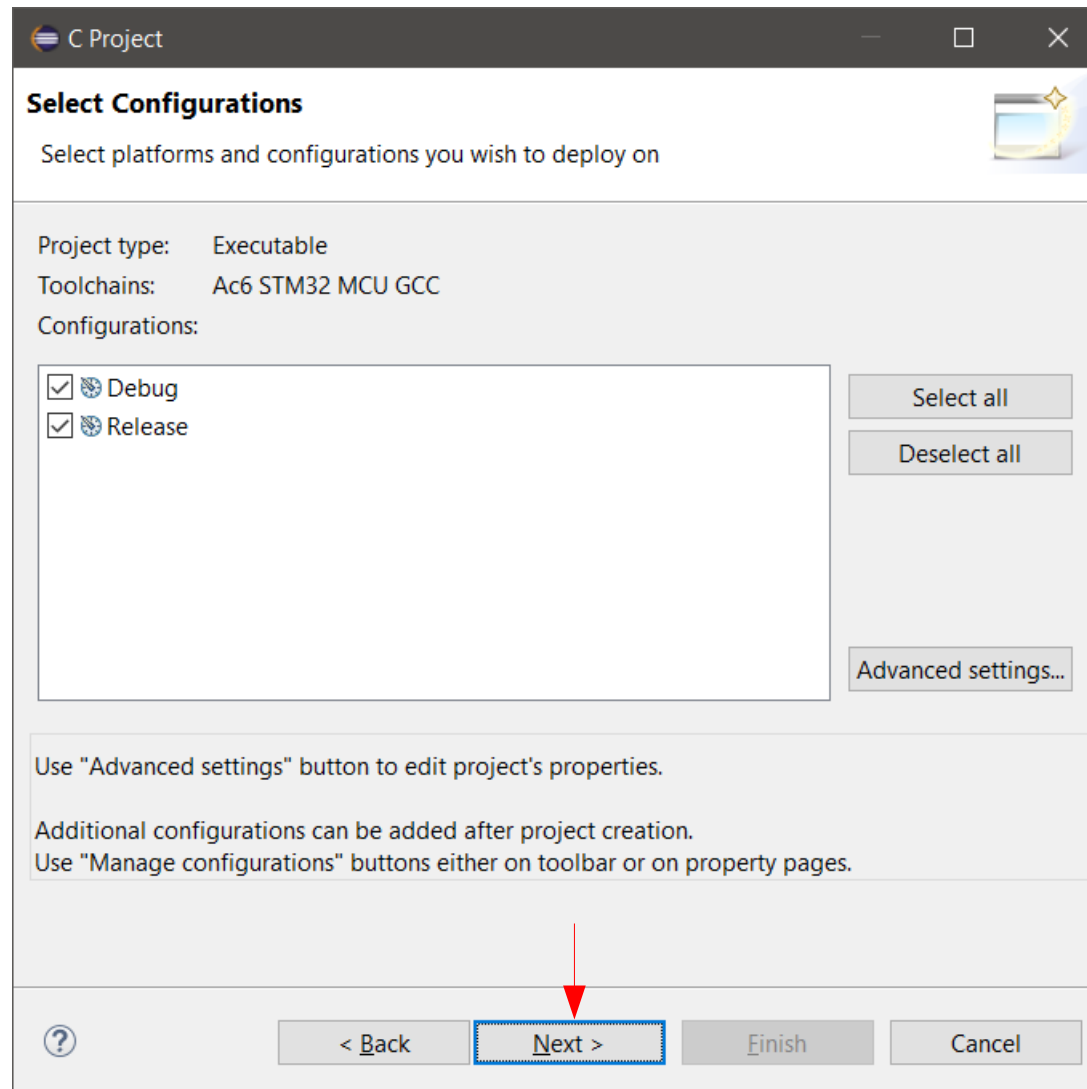
Creating a New Project on System Workbench

- On the new window, give a name for your project, select **Ac6 STM32 MCU Project** → **Ac6 STM32 MCU GCC**, and click on **Next**.



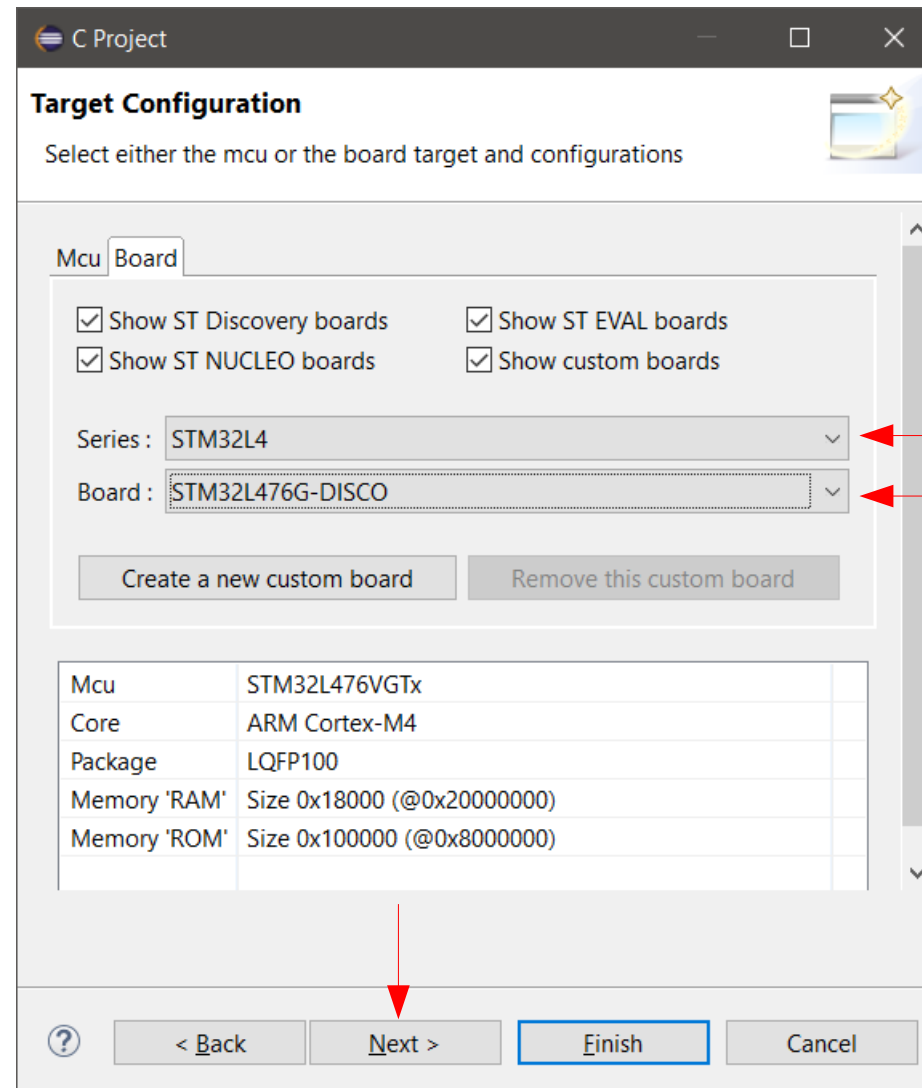
Creating a New Project on System Workbench

- On the window called **Select Configurations**, do not change anything, and just click on the **Next** button.



Creating a New Project on System Workbench

- On the window called **Target Configuration**, make sure everything is identical to the picture below, and click on **Next**:



C Project

Target Configuration

Select either the mcu or the board target and configurations

Mcu Board

☒ Show ST Discovery boards ☒ Show ST EVAL boards
☒ Show ST NUCLEO boards ☒ Show custom boards

Series : STM32L4
Board : STM32L476G-DISCO

Create a new custom board Remove this custom board

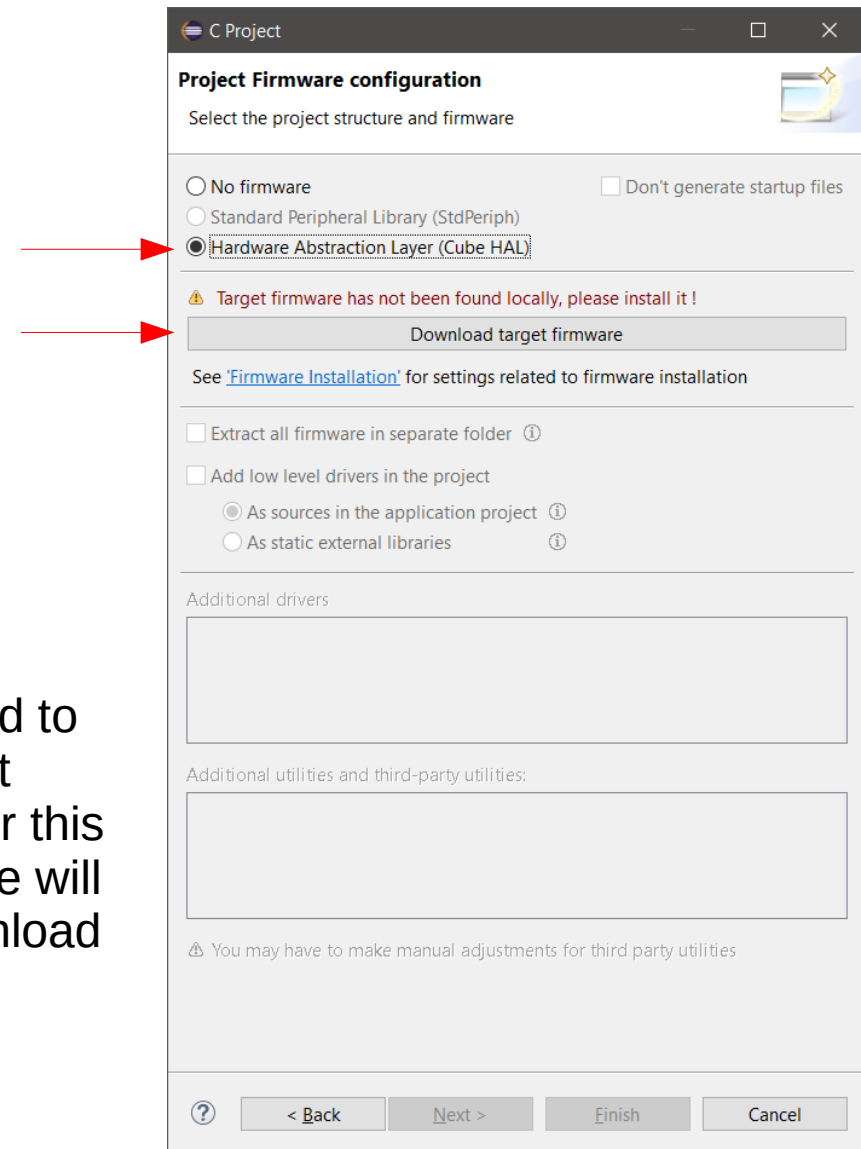
Mcu	STM32L476VGTx
Core	ARM Cortex-M4
Package	LQFP100
Memory 'RAM'	Size 0x18000 (@0x20000000)
Memory 'ROM'	Size 0x100000 (@0x8000000)

? < Back **Next >** Finish Cancel

DON'T click on
Finish at this
point!

Creating a New Project on System Workbench

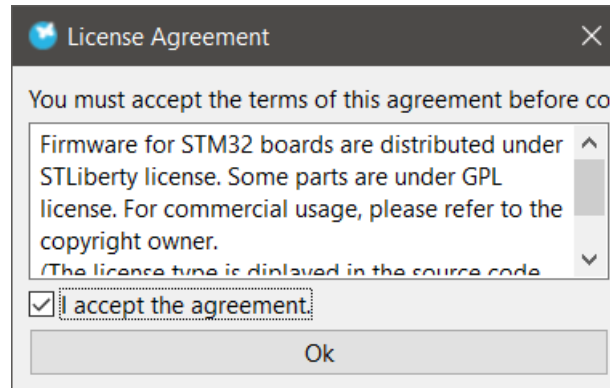
- On Project Firmware Configuration, select Hardware Abstraction Layer (Cube HAL), and click on Download target firmware.



Note: you only need to download the target firmware once. After this first download, there will be no need to download again.

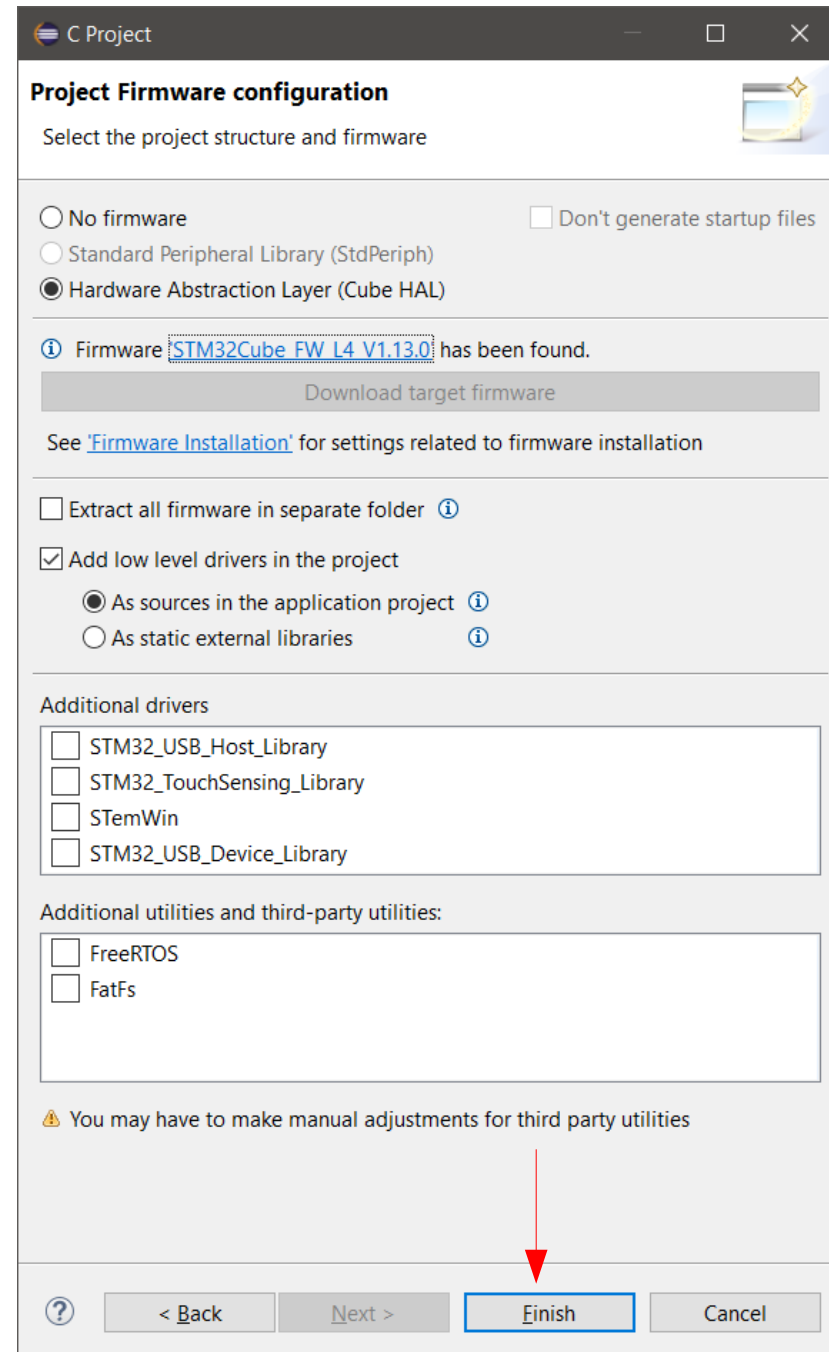
Creating a New Project on System Workbench

- A **License Agreement** will pop-up, check **I accept the agreement**, and click on **OK**.



Creating a New Project on System Workbench

- Once the download is completed, you can click on **Finish**.
- Do not change the other configurations!



C Project

Project Firmware configuration

Select the project structure and firmware

☐ No firmware ☐ Don't generate startup files

☐ Standard Peripheral Library (StdPeriph)

☒ Hardware Abstraction Layer (Cube HAL)

i Firmware STM32Cube_FW_L4_V1.13.0 has been found.

Download target firmware

See ['Firmware Installation'](#) for settings related to firmware installation

☐ Extract all firmware in separate folder **i**

☒ Add low level drivers in the project

☒ As sources in the application project **i**

☐ As static external libraries **i**

Additional drivers

☐ STM32_USB_Host_Library

☐ STM32_TouchSensing_Library

☐ STemWin

☐ STM32_USB_Device_Library

Additional utilities and third-party utilities:

☐ FreeRTOS

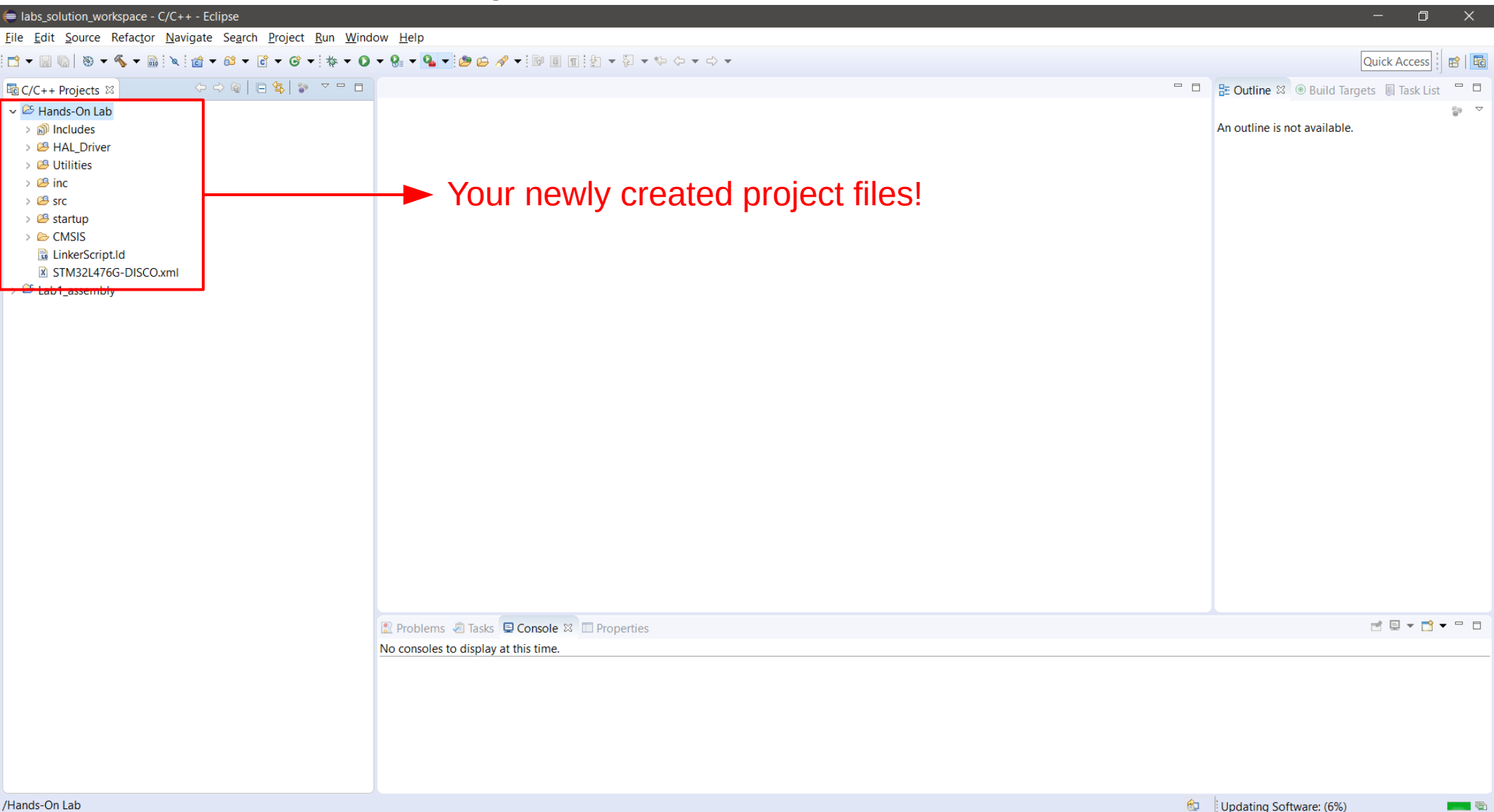
☐ FatFs

w You may have to make manual adjustments for third party utilities

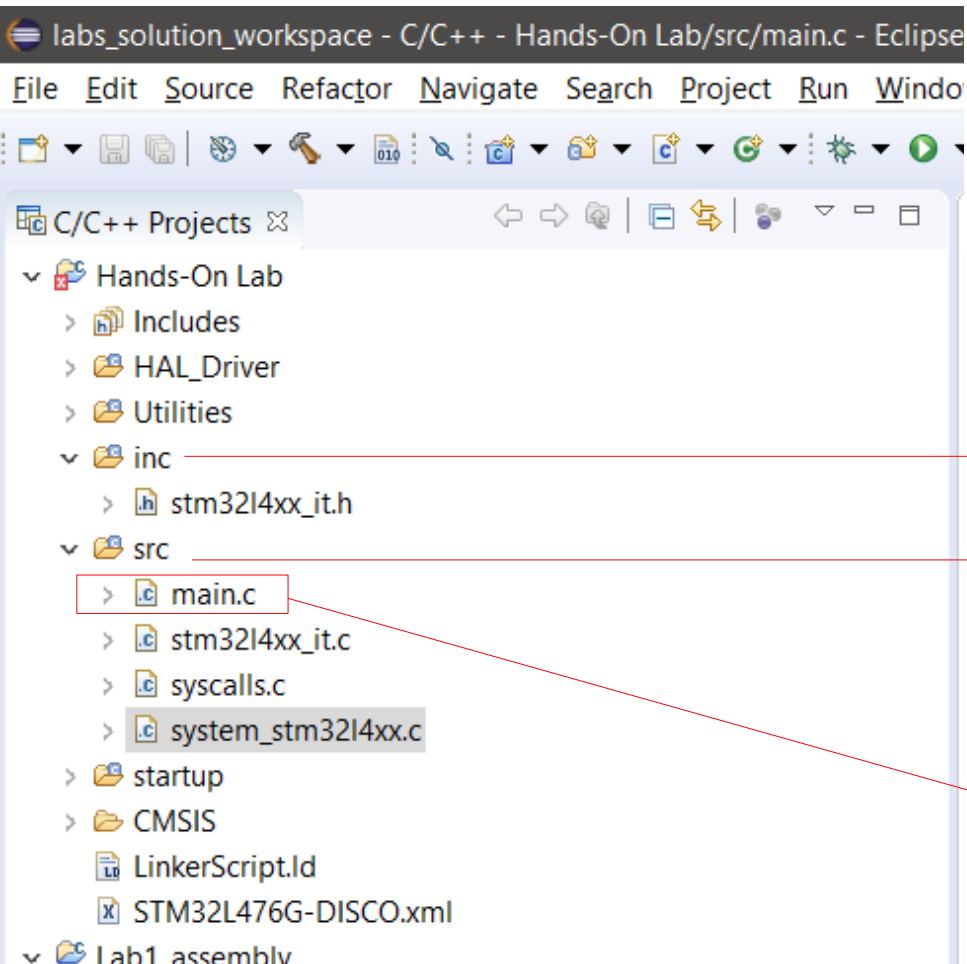
? **< Back** **Next >** **Finish** **Cancel**

Creating a New Project on System Workbench

- Now, your project is created and you will have access to all code files on the panel on the left in the IDE.



Creating a New Project on System Workbench



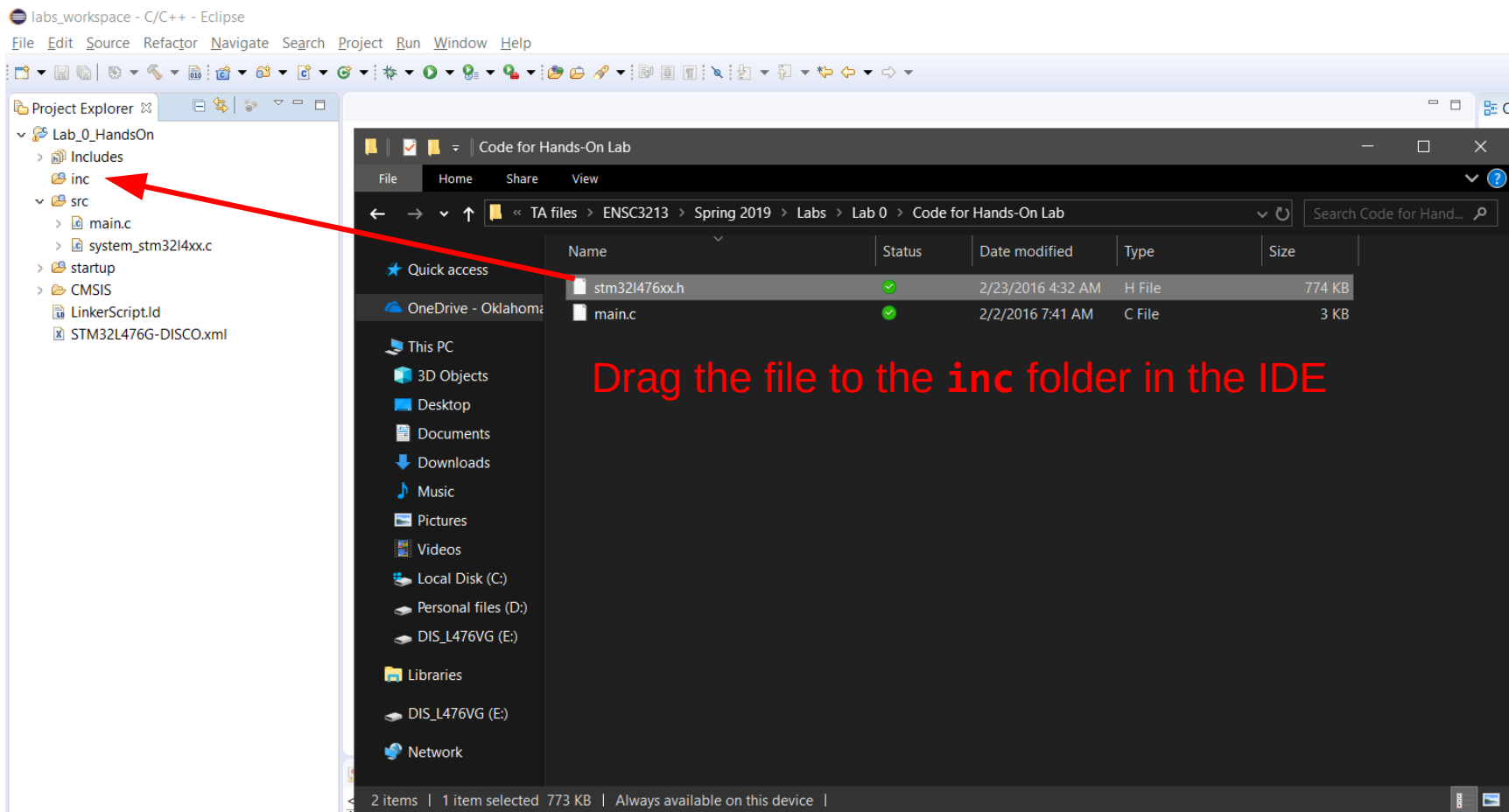
The **inc** folder will contain all our **.h** files.

The **src** folder will contain all our **.c** files and **.s** files.

Our **main.c** will be created inside the **src** folder.

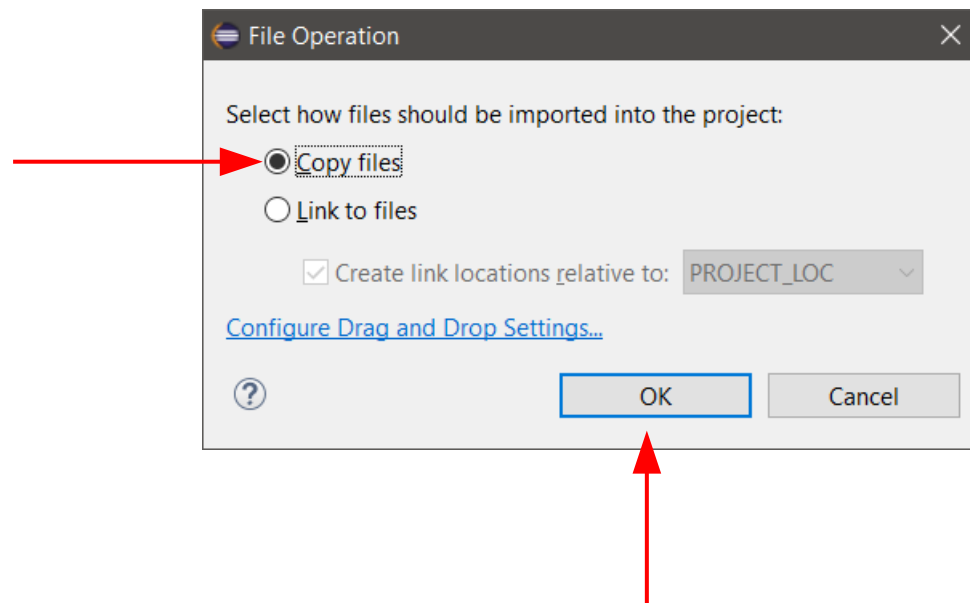
Creating a New Project on System Workbench

- The final step is to move the given file **stm32l476xx.h** to the **inc** folder. You can do this by clicking and dragging the file.



Creating a New Project on System Workbench

- The IDE will ask if you want to copy or link the file. Click on **Copy files** and, then, on **OK**.



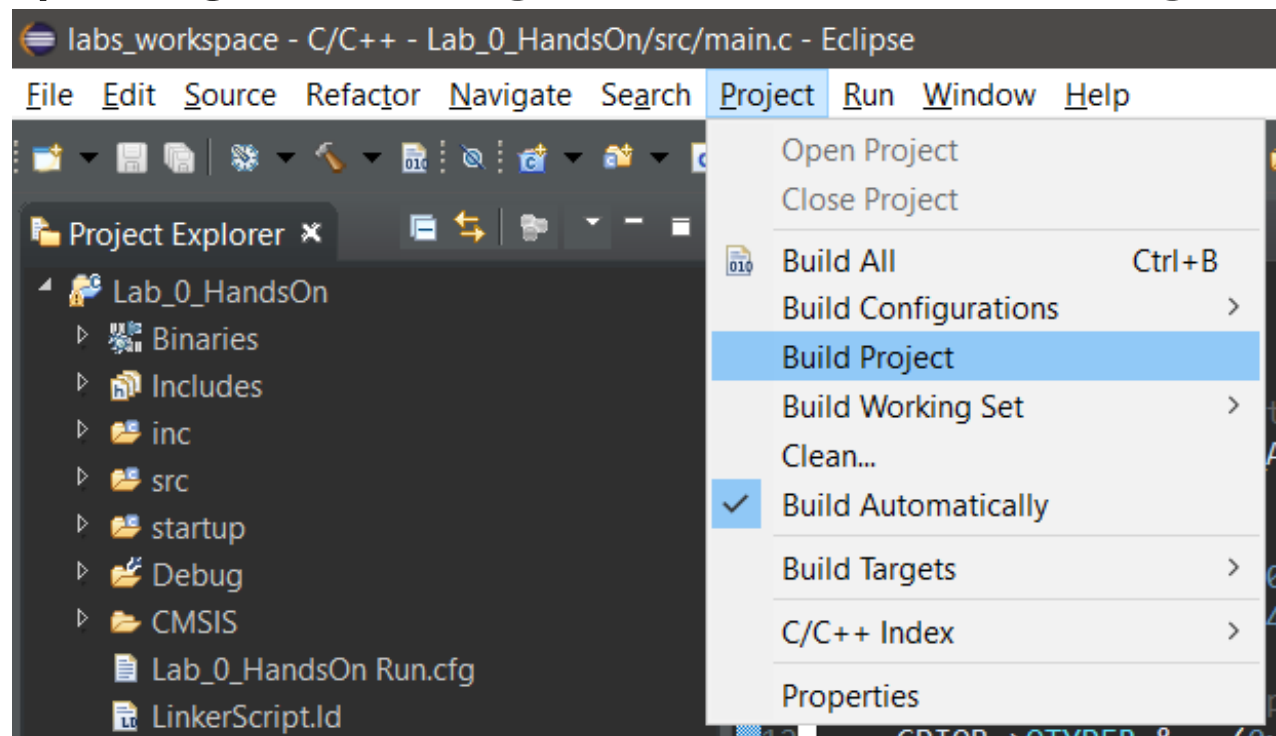


Creating a New Project on System Workbench

- Now, you can double click on the file `main.c` and start writing your code! Finally!

Compiling your code on System Workbench

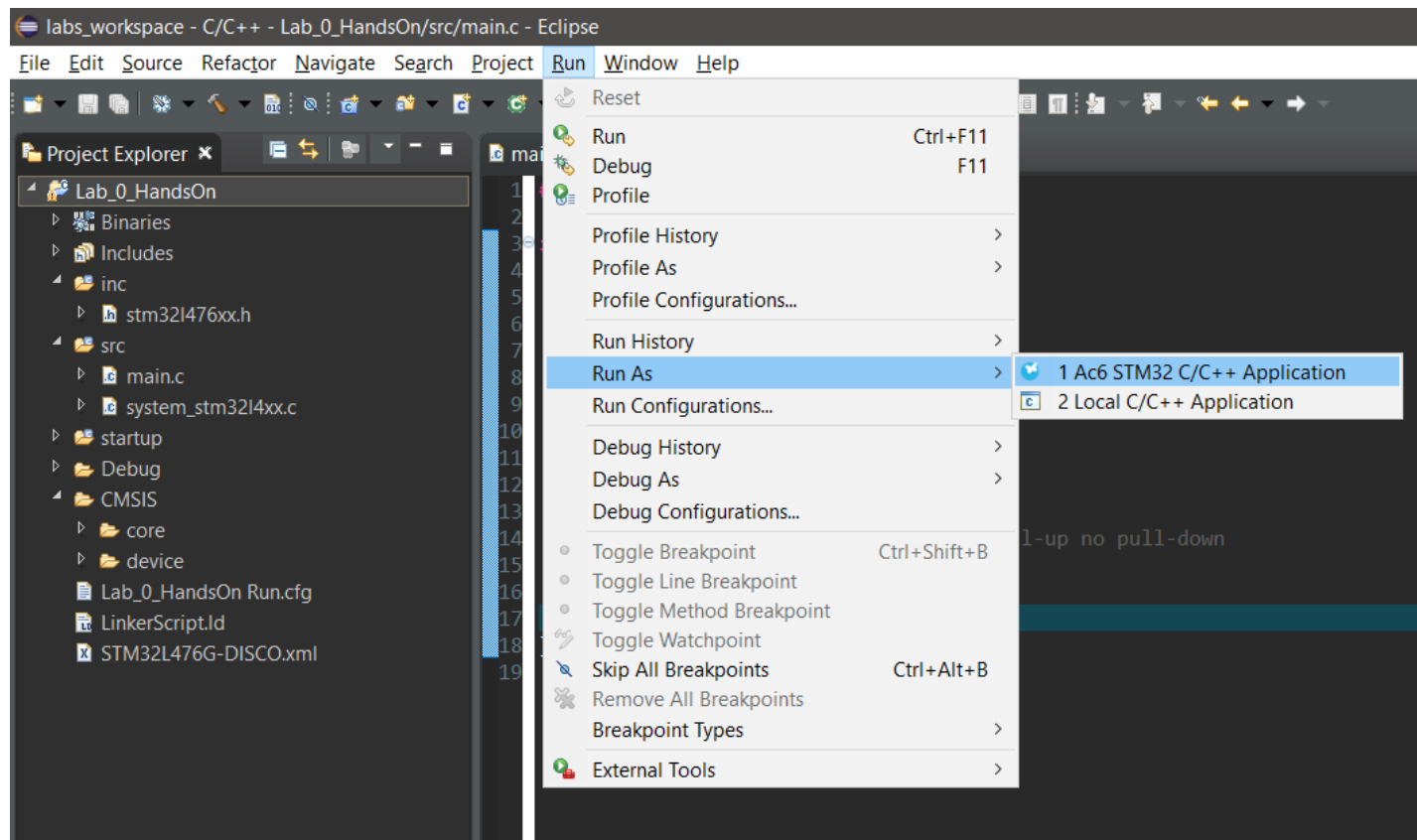
- After you're done writing your code, you will need to **compile** it, and **upload** it to the development kit.
 - To compile, go to **Project** → **Build Project**.



- If everything is correct with your code, you will see the message **Build Finished** and no errors in the **Console** window.

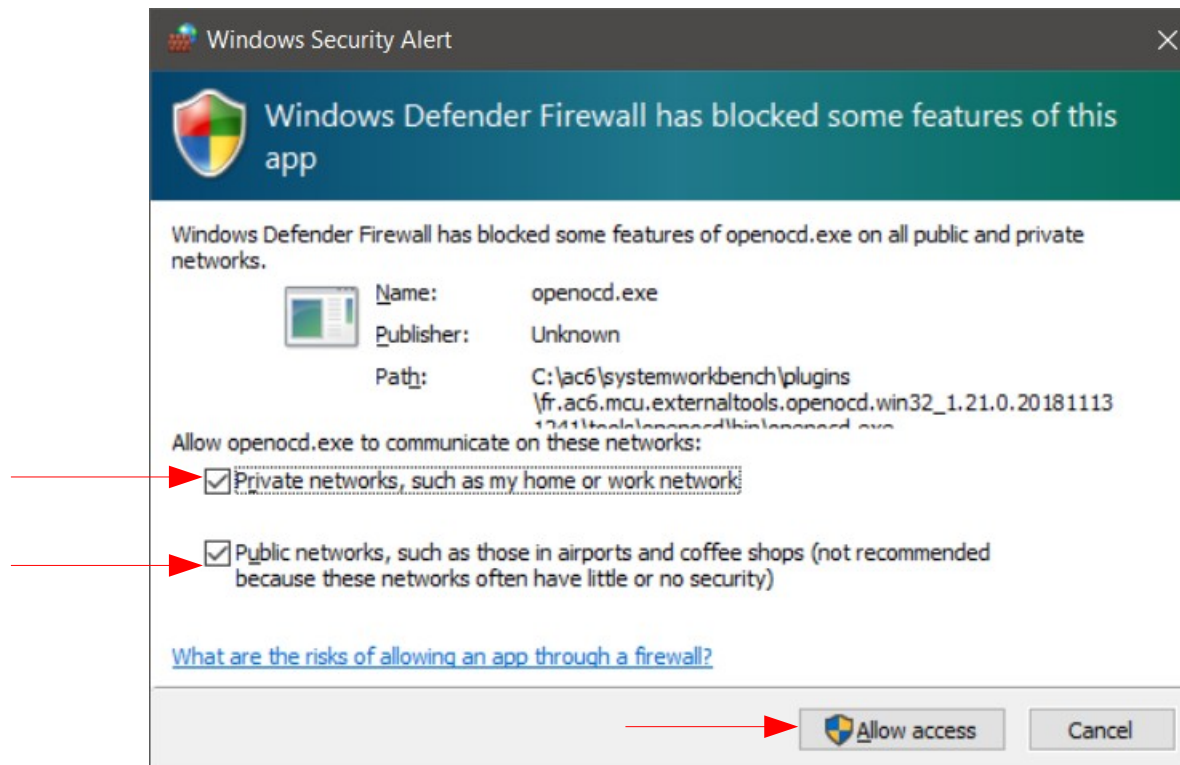
Uploading your code using System Workbench

- To upload your newly compiled code, go to **Run** → **Run As** → **Ac6 STM32 C/C++ Application**.
- This will upload your compiled code and reset the development kit.



Uploading your code using System Workbench

- When uploading, the application may ask for permission to use the network. Make sure you allow access.





- The **debug** interface of most development boards, such as **STM32L4 Discovery Kit**, often provides a **USB mass storage interface**. When a board is connected to a computer, it is automatically mounted as a USB drive.
- To program the board, we only need to copy the generated **.bin** file to the mounted USB drive.

Manually Programming and Debugging the Board



- **OpenOCD (Open On-Chip Debugger)** is an open-source software that is widely used for debugging and downloading executables to microprocessors. **OpenOCD** runs as a server (also known as a **daemon**) on a host computer and serves two purposes:
 - It receives commands from either **Telnet** or **gdb** via TCP/IP connection.
 - It translates commands received to **JTAG/SW** commands, and sends them to the target ARM Cortex-M processor via the hardware debugger.

