

Lecture 3: Review of C

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The General Form of a Simple Program

- Simple **C** programs have the form:

directives

```
int main(void)
{
    statements
}
```

- **C** uses { and } in much the same way that some other languages use words like **begin** and **end**.
- Even the simplest **C** programs rely on three key language features:
 - **Directives**
 - **Functions**
 - **Statements**



- Before a **C** program is compiled, it is first edited by a **preprocessor**.
- Commands intended for the **preprocessor** are called **directives**.
- Example:

```
#include <stdio.h>
```

- **<stdio.h>** is a **header** containing information about **C**'s standard I/O library.
- Directives always begin with a # character.
- By default, directives are one line long; there's no semicolon or other special marker at the end.



Directives

- Our standard directive will be the following:
#include “stm321476xx.h”
- The **stm321476xx.h** file contains:
 - Data structures and the address mapping for all peripherals.
 - Peripheral's registers declarations and bits definition.
 - Macros to access peripheral's registers hardware.
- Example:

```
***** Bit definition for RCC_AHB2ENR register *****

#define RCC_AHB2ENR_GPIOAEN ((uint32_t)0x00000001U)
#define RCC_AHB2ENR_GPIOBEN ((uint32_t)0x00000002U)
#define RCC_AHB2ENR_GPIOCEN ((uint32_t)0x00000004U)
#define RCC_AHB2ENR_GPIODEN ((uint32_t)0x00000008U)
#define RCC_AHB2ENR_GPIOEEN ((uint32_t)0x00000010U)
#define RCC_AHB2ENR_GPIOFEN ((uint32_t)0x00000020U)
#define RCC_AHB2ENR_GPIOGEN ((uint32_t)0x00000040U)
#define RCC_AHB2ENR_GPIOHEN ((uint32_t)0x00000080U)
#define RCC_AHB2ENR_OTGFSEN ((uint32_t)0x00001000U)
#define RCC_AHB2ENR_ADCEN ((uint32_t)0x00002000U)
#define RCC_AHB2ENR RNGEN ((uint32_t)0x00040000U)
```



Functions

- A **function** is a series of statements that have been grouped together and given a name.
- **Library functions** are provided as part of the **C** implementation.
- A function that computes a value uses a **return** statement to specify what value it “returns”:

```
return x + 1;
```



The **main** Function

- The **main** function is mandatory.
- **main** is special: it gets called automatically when the program is executed.
- **main** returns a status code; the value 0 indicates normal program termination.
- If there's no **return** statement at the end of the **main** function, many compilers will produce a warning message.
 - The compiler used in our labs does not require a **return** statement at the end of the **main** function.



Statements

- A **statement** is a command to be executed when the program runs.
- Asking a function to perform its assigned task is known as **calling** the function.
- For example, to display a string we call the **printf** function:
printf("To C, or not to C: that is the question.\n");



Printing Strings

- When the **printf** function displays a **string literal** - characters enclosed in double quotation marks - it doesn't show the quotation marks.
- **printf** doesn't automatically advance to the next output line when it finishes printing.
- To make **printf** advance one line, include `\n` (the **new-Line character**) in the string to be printed.
- However, when programming at the Bare Metal Layer, we do not have access to the **printf** function.
- When developing for embedded systems, debugging is done by manually verifying the values of the processor registers.



Comments

- A **comment** begins with `/*` and end with `*/`.

```
/* This is a comment */
```

- A single line comment can be written using `//`. For example:

```
// This is a single line comment
```

- Comments may appear almost anywhere in a program, either on separate lines or on the same lines as other program text.
- Comments may extend over more than one line.

```
/* Name: pun.c  
Purpose: Prints a bad pun.  
Author: K. N. King */
```



Overall Program Structure

```
#include "stm32l476xx.h"  
  
int main(void){  
    RCC->AHB2ENR |= 0x02; // Enable clock of Port B  
  
    GPIOB->MODER &= ~(3<<4); // Clear mode bits  
    GPIOB->MODER |= 1<<4; // Set mode to output  
  
    GPIOB->OTYPER &= ~(1<<2); // Select push-pull output  
  
    GPIOB->ODR |= 1 << 2; // Output 1 to turn on red LED  
  
    while(1) {  
    }  
}
```

Indentation is important to keep your code organized. We normally use a single Tab or four Spaces.

All of your programming logic goes inside this dead loop.

This **directive** will always be used in all our programs!

Always use **int main(void)**!

Comments

The red lines are the **statements** of this program.

Remember: when modifying registers, always use **bitwise operations**!



Variables and Assignment

- Most programs need a way to store data temporarily during program execution.
 - Our brain does this as well to remember key events in our life!
 - Or, perhaps, our phone number or home address.
- These storage locations are called **variables**.
- **Variables** must be **declared** before they are used.



Variable Types

- Every variable must have a **type**.
- C has a wide variety of types, including **int** and **float**.
- A variable of type **int** (short for *integer*) can store a whole number such as **0**, **1**, **392**, or **-2553**.
 - The largest **int** value is typically **2,147,483,647** but can be as small as **32,767**.
- A variable of type **float** (short for *floating-point*) can store much larger numbers than an **int** variable.
- Also, a **float** variable can store numbers with digits after the decimal point, like **379.125**.
- Drawbacks of **float** variables:
 - Slower arithmetic
 - Approximate nature of **float** values



Variable Types

- Variables can be declared one at a time:
int height;
float profit;
- Alternatively, several can be declared at the same time:
int height, length, width, volume;
float profit, loss;



Variable Types

- When dealing with the **32-bit registers** in our **ARM Cortex-M4** processor, we are going to use a special variable type called **fixed width integer types**.
- These are the most common ones we are going to be using:
 - **uint8_t**
 - **uint16_t**
 - **uint32_t**
 - **uint64_t**
- These represent **unsigned integer type** with *width of exactly 8, 16, 32 and 64 bits*, respectively.



Variable Types

- When `main` contains **declarations**, these must precede **statements**:

```
int main(void)
{
    declarations
    statements
}
```



Defining Names for Constants

- If you are writing a program that use the same constant number throughout your code, you can use a feature called **macro definition**.
- For example:

```
#define RED_LED_PIN 2
```

- The above line will make the name **RED_LED_PIN** equal to the numeral 2.
- When a program is compiled, the **preprocessor** replaces each **macro** by the value that it represents.
- The value of a macro can be an expression:

```
#define RECIPROCAL_OF_PI (1.0f / 3.14159f)
```

- If it contains operators, the expression should be enclosed in parentheses.
- Using only upper-case letters in macro names is a common convention.

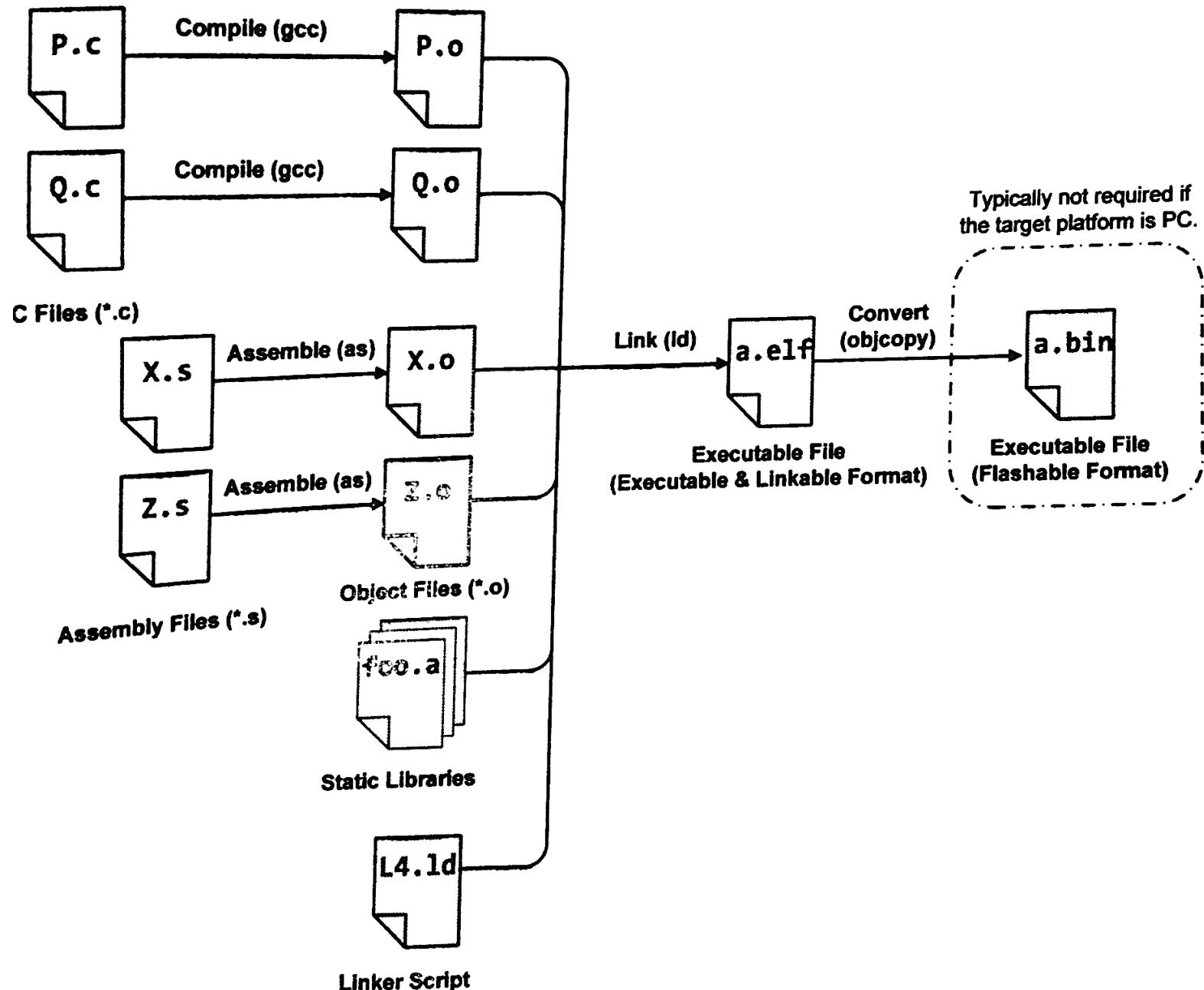


- The **GNU Compiler Collection (GCC)** consists of a suite of free, open-source, and widely used programming and debugging tools for many types of processors, such as x86/x64, ARM, MIPS, and AVR. The following lists a few important tools.
 - The **GNU C compiler (gcc)** translates a **C** source file to an assembly file or to an object file (machine code).
 - The **assembler (as)** converts an assembly program to an object file.
 - The **linker (ld)** links object files and pre-compiled libraries into an executable file in a format such as **ELF (Executable and Linkable Format)**.



- To program microprocessors, flash programmers often require us to convert the **ELF** format to a specific binary format that can be directly written to **flash** or **ROM**. We can use **objcopy** to achieve the conversion.
- The **debugger (gdb)** allow us to debug a program step by step.

GNU Compiler





GNU Compiler

- Commands to build the project given in the previous slide:

```
gcc -c -g -o P.o P.c
```

```
gcc -c -g -o Q.o Q.c
```

```
as -g -o X.o X.s
```

```
as -g -o X.o X.s
```

```
as -g -o Z.o Z.s
```

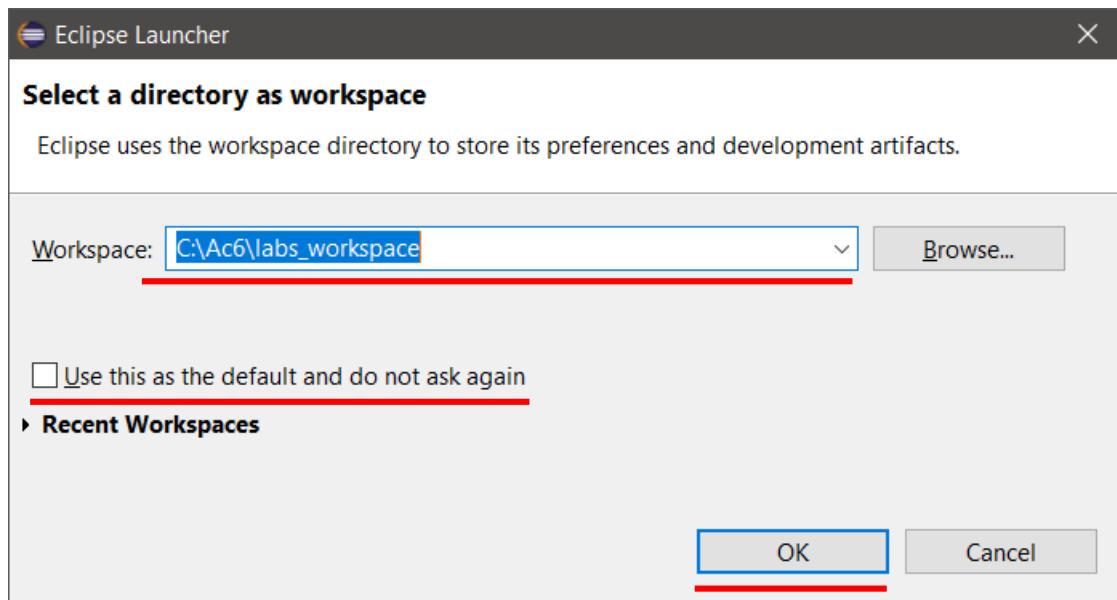
```
ld TL4.ld -lfoo -o a.elf P.o Q.o X.o Q.o
```

```
objcopy -O binary a.elf a.bin
```



Creating a New Project on System Workbench

- The first time you open the System Workbench IDE, you will have to select a folder where all your projects will be located.



Important: Your workspace folder **CANNOT** contain any spaces in its name! Otherwise, you will face compilation errors.

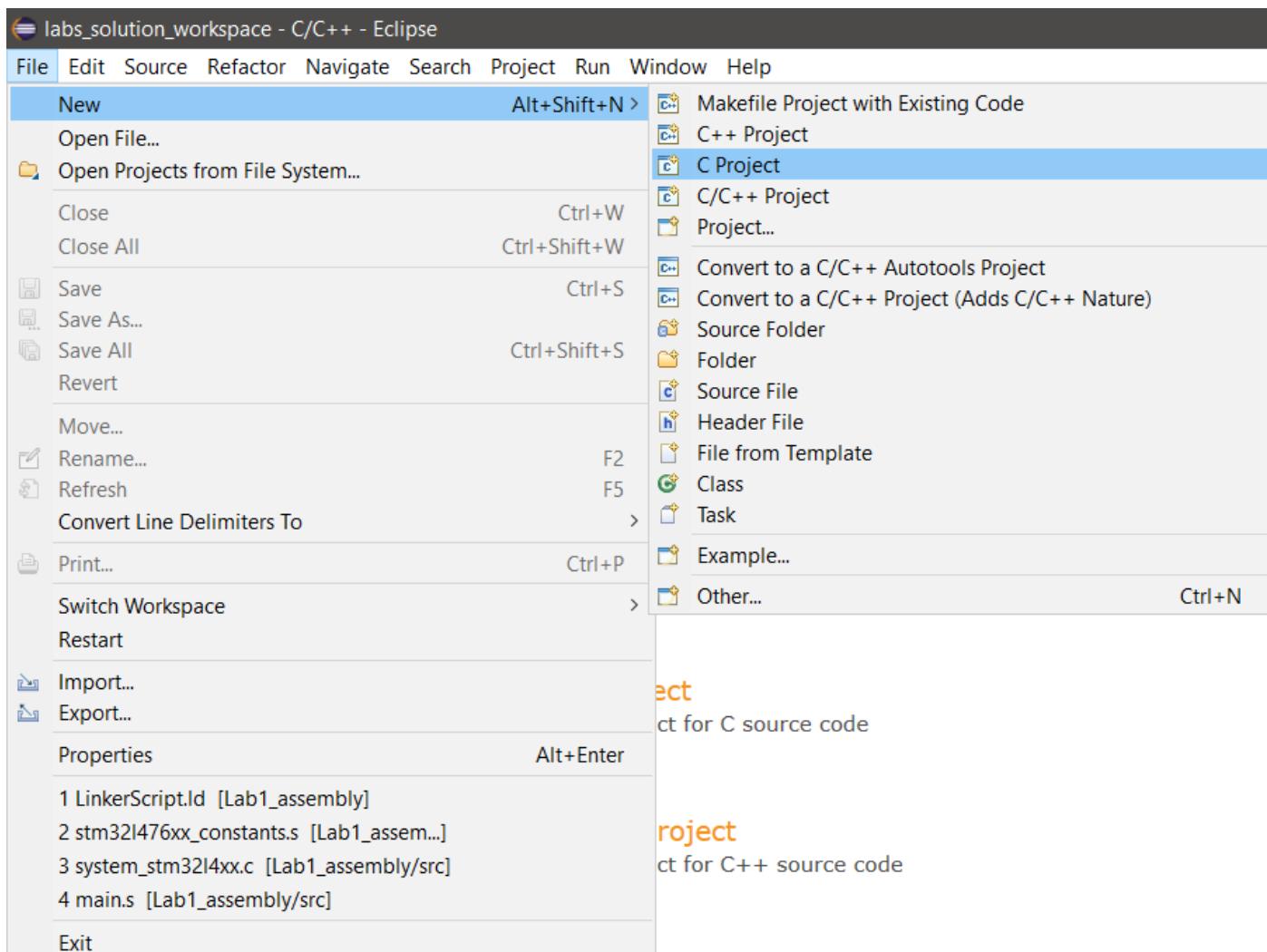
It is recommended to create a folder in your **C:** unit.

- If you don't want to always the folder every time you open the IDE, you can check the box **Use this as the default and do not ask again**.
- Click on the **OK** button to open the IDE.



Creating a New Project on System Workbench

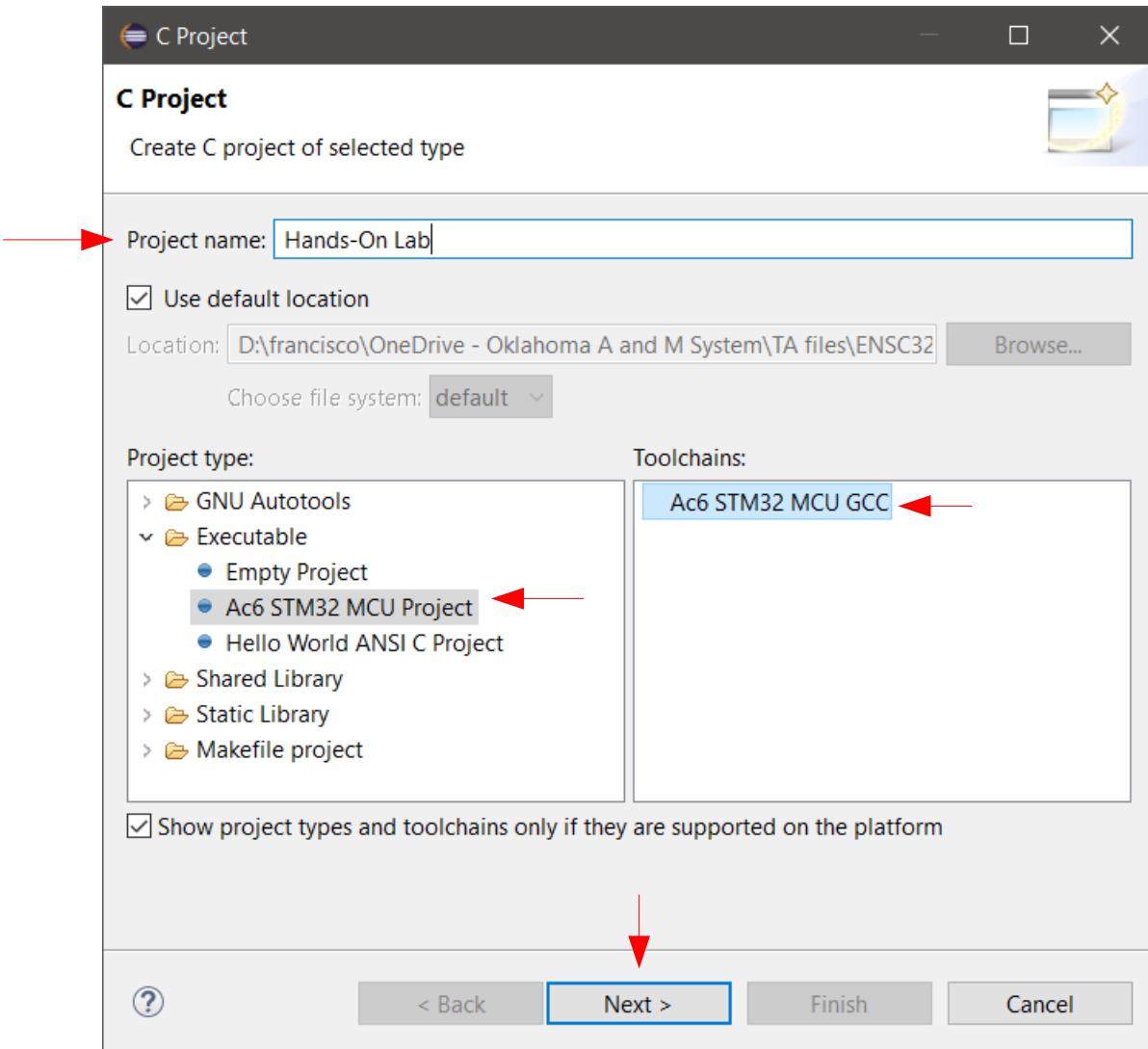
- Once the IDE has opened, you need to select **File** → **New** → **C Project**.





Creating a New Project on System Workbench

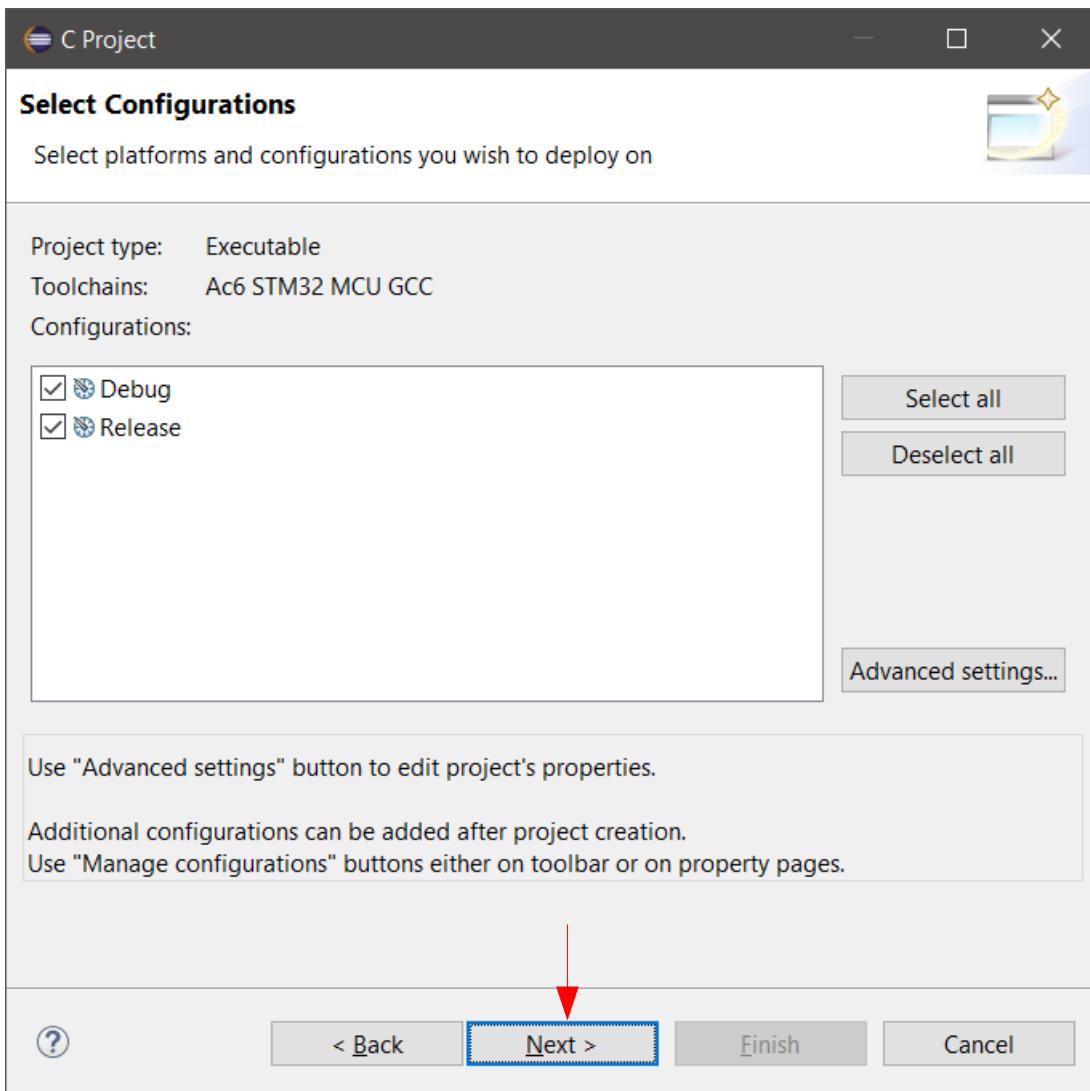
- On the new window, give a name for your project, select **Ac6 STM32 MCU Project** → **Ac6 STM32 MCU GCC**, and click on **Next**.





Creating a New Project on System Workbench

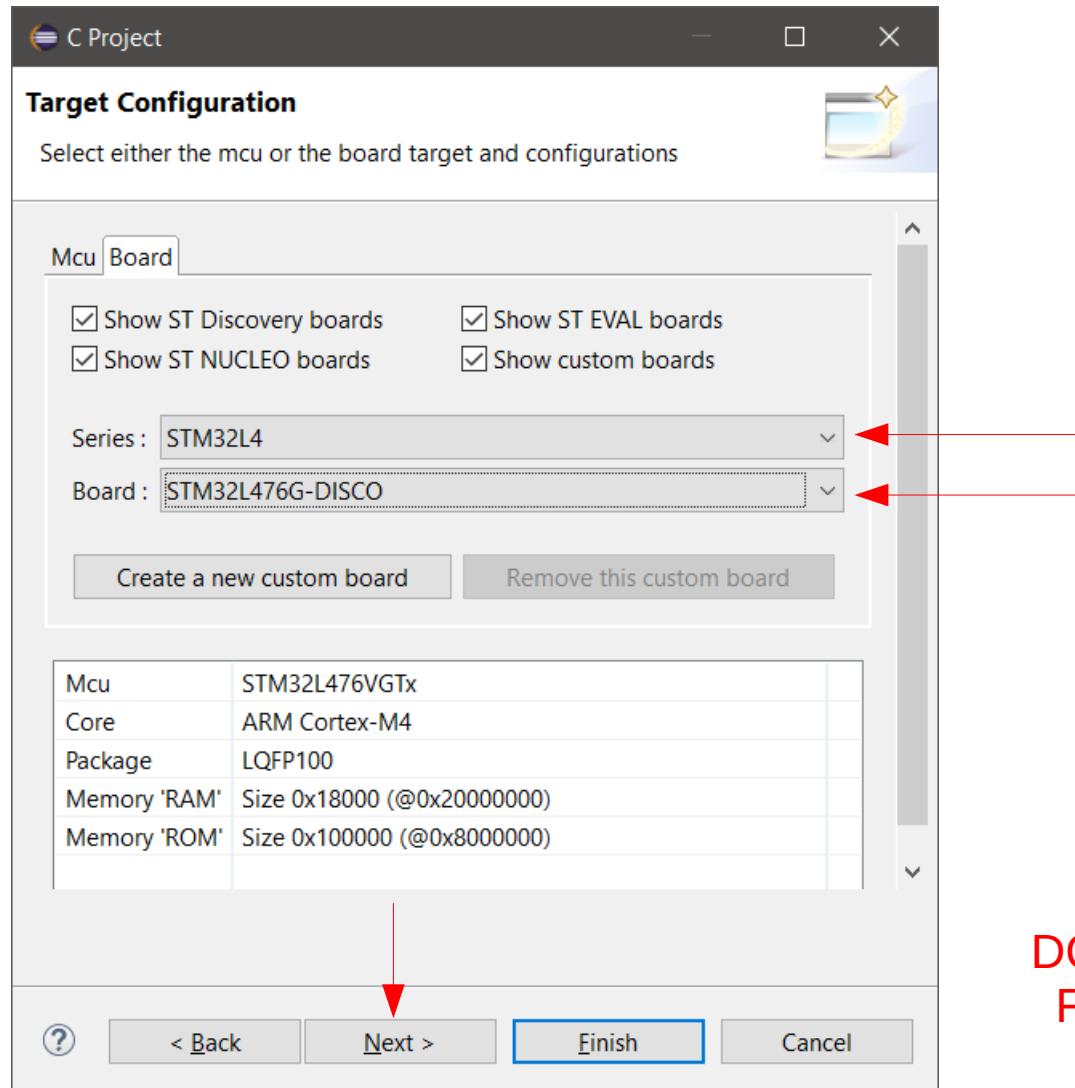
- On the window called **Select Configurations**, do not change anything, and just click on the **Next** button.





Creating a New Project on System Workbench

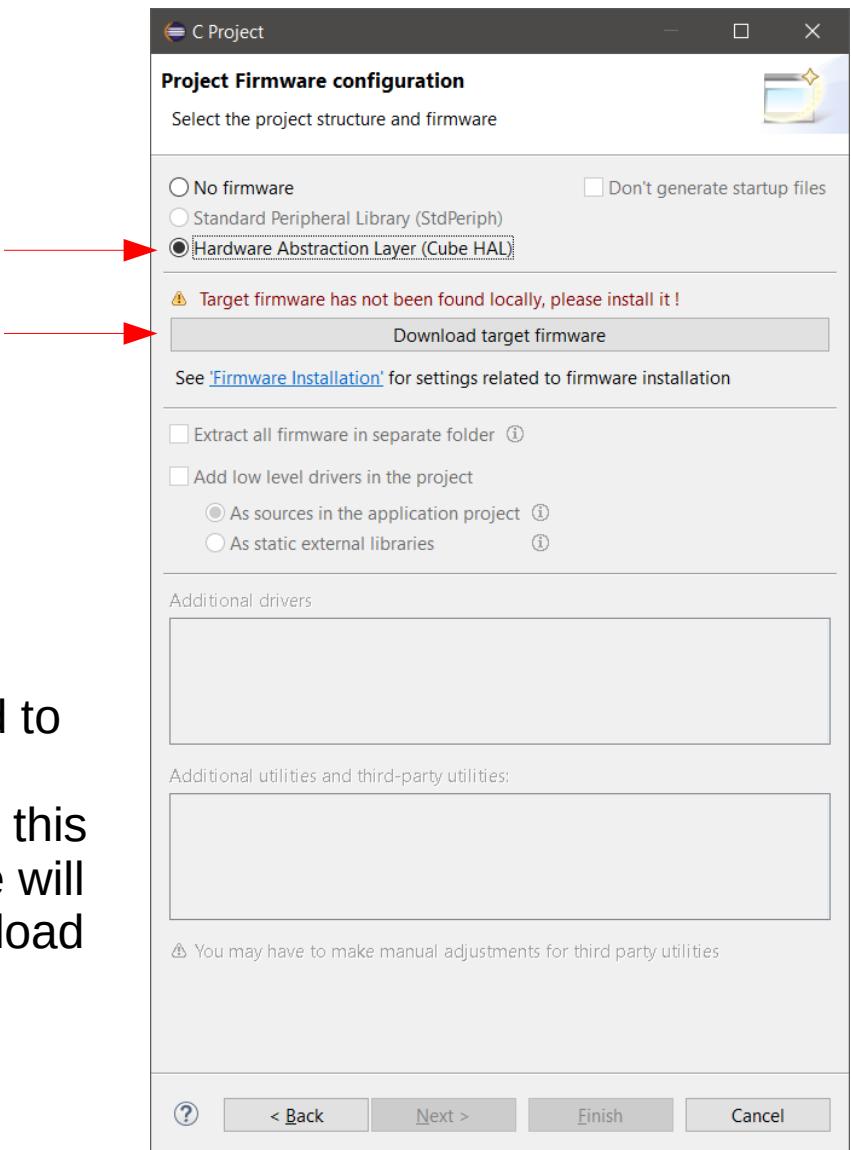
- On the window called **Target Configuration**, make sure everything is identical to the picture below, and click on **Next:**





Creating a New Project on System Workbench

- On Project Firmware Configuration, select Hardware Abstraction Layer (Cube HAL), and click on Download target firmware.

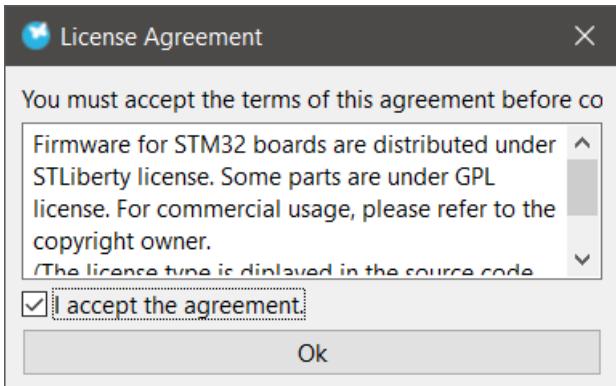


Note: you only need to download the target firmware once. After this first download, there will be no need to download again.



Creating a New Project on System Workbench

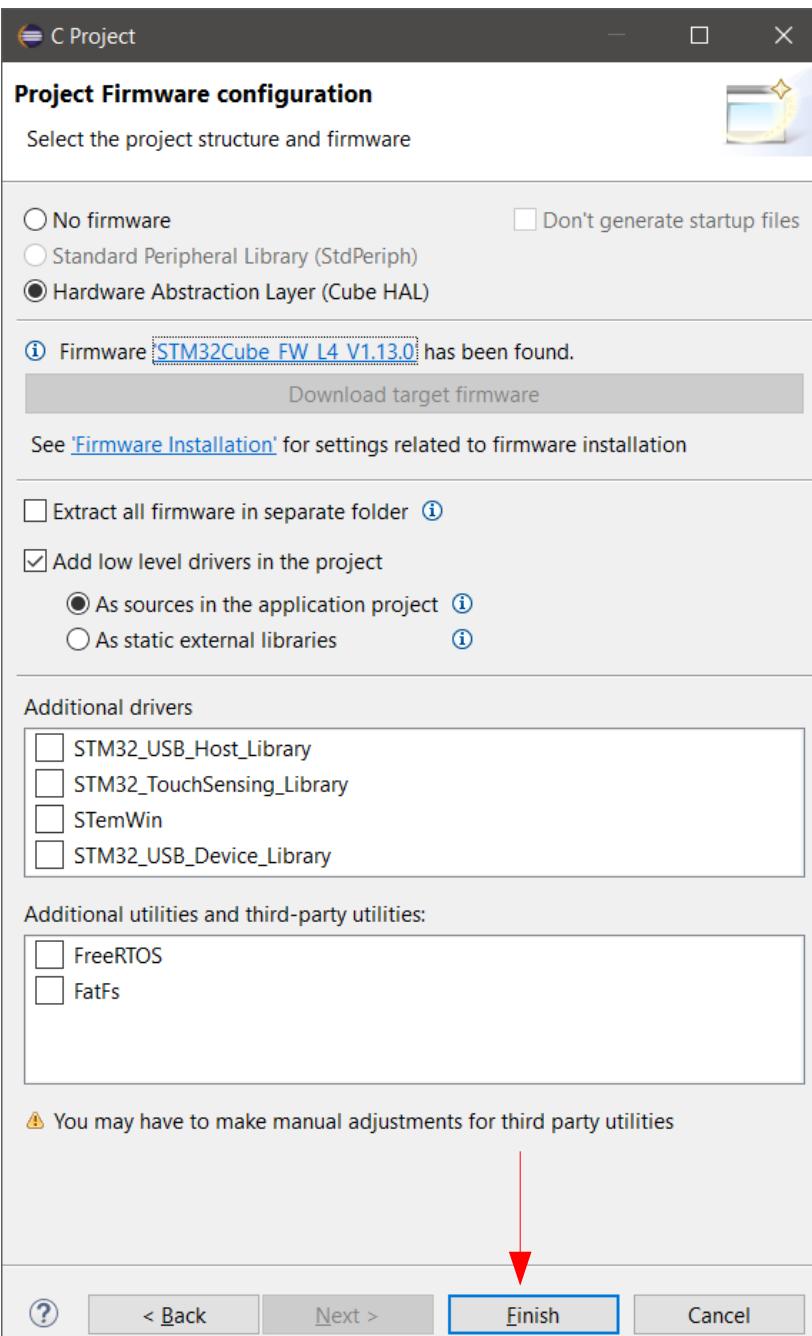
- A **License Agreement** will pop-up, check **I accept the agreement**, and click on **OK**.





Creating a New Project on System Workbench

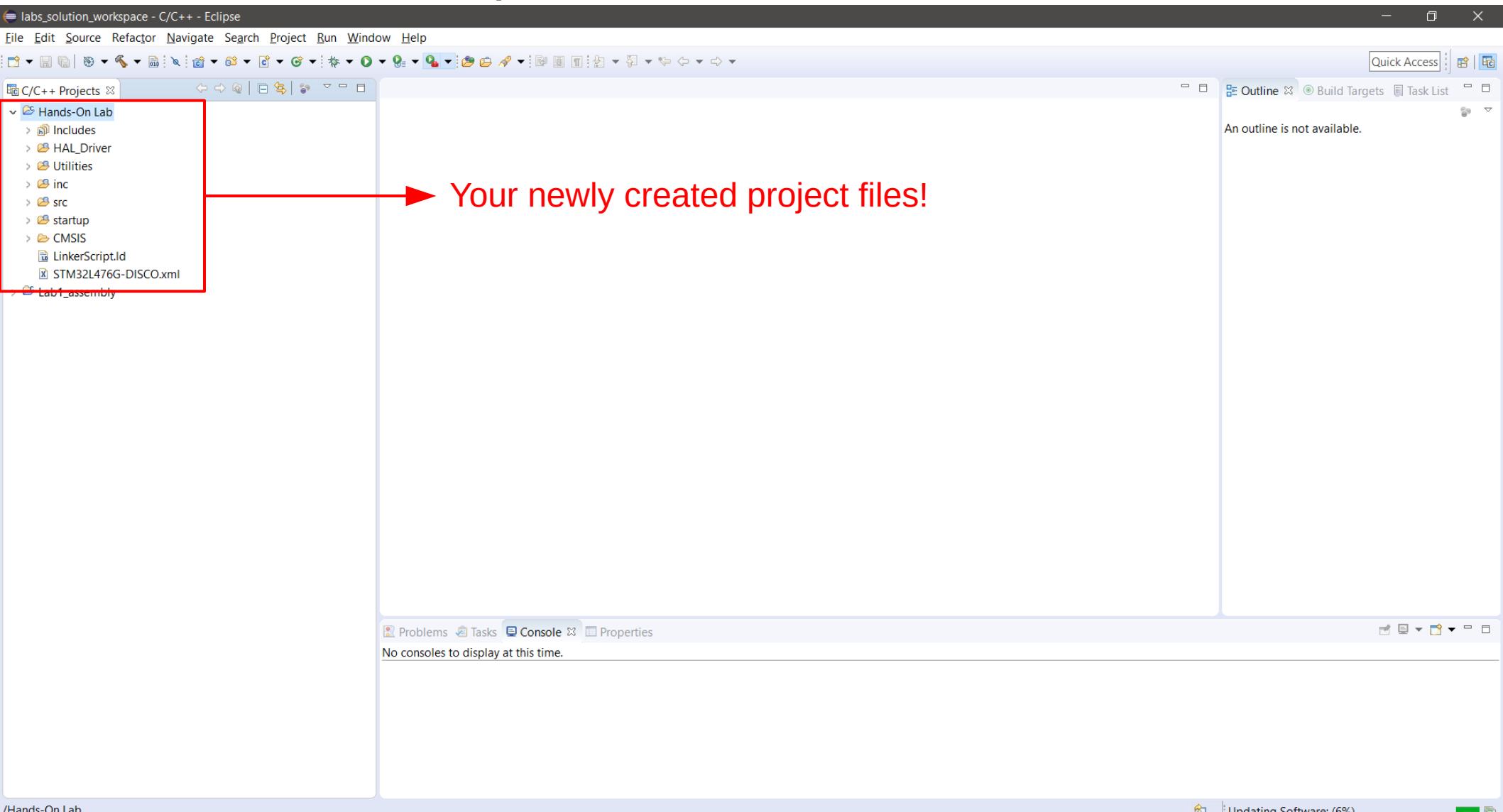
- Once the download is completed, you can click on **Finish**.
- Do not change the other configurations!





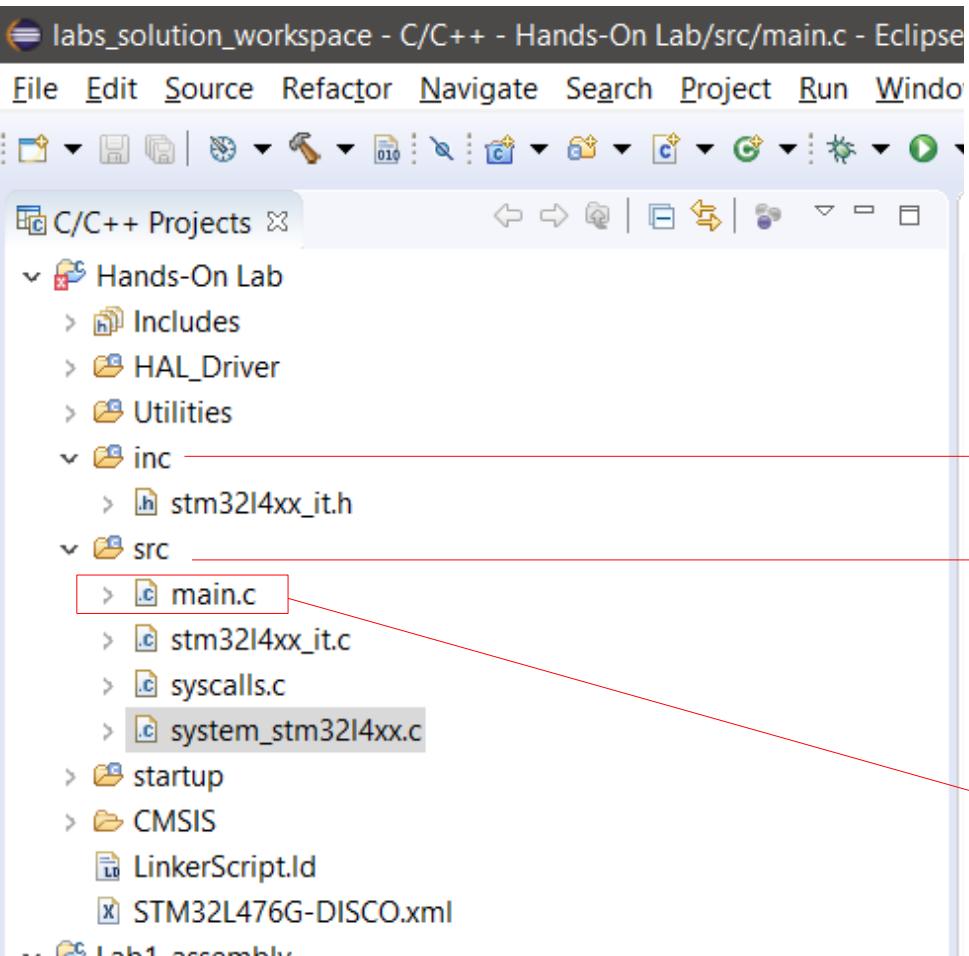
Creating a New Project on System Workbench

- Now, your project is created and you will have access to all code files on the panel on the left in the IDE.





Creating a New Project on System Workbench



The **inc** folder will contain all our **.h** files.

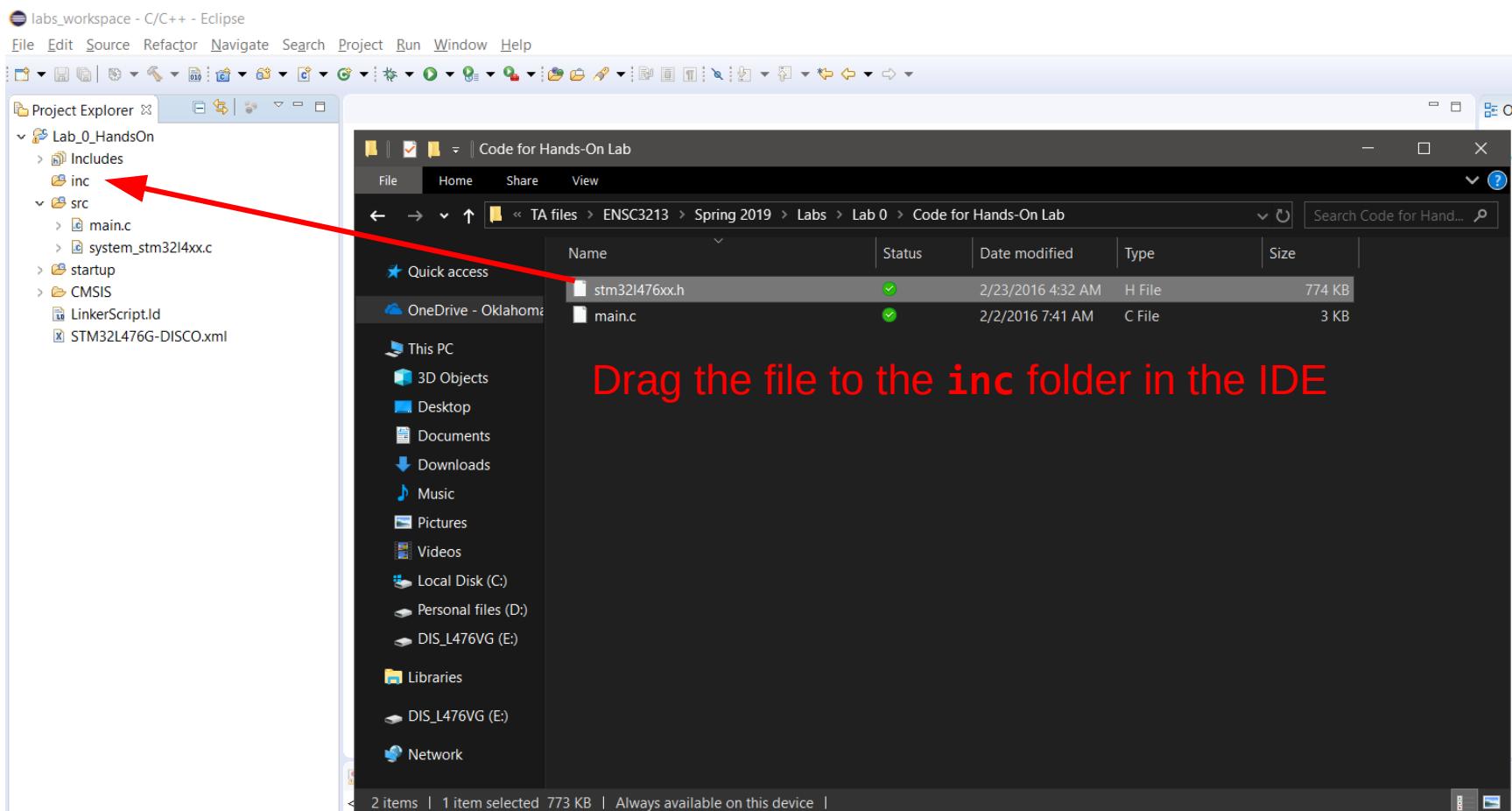
The **src** folder will contain all our **.c** files and **.s** files.

Our **main.c** will be created inside the **src** folder.



Creating a New Project on System Workbench

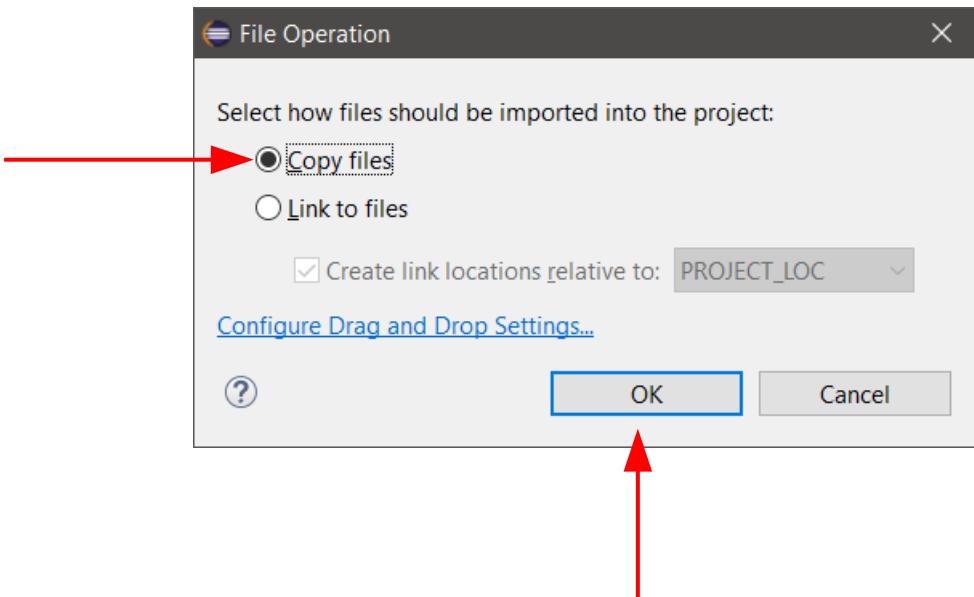
- The final step is to move the given file **stm32l476xx.h** to the **inc** folder. You can do this by clicking and dragging the file.





Creating a New Project on System Workbench

- The IDE will ask if you want to copy or link the file. Click on **Copy files** and, then, on **OK**.



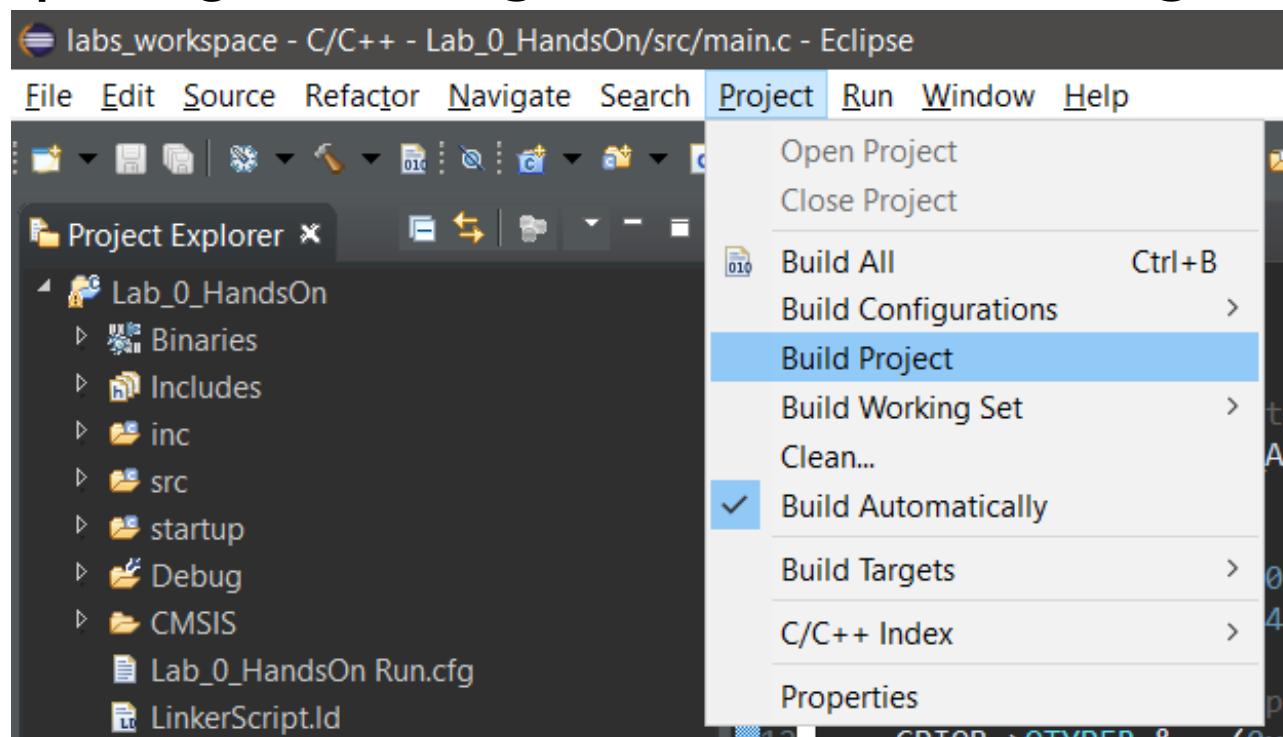


Creating a New Project on System Workbench

- Now, you can double click on the file **main.c** and start writing your code! Finally!

Compiling your code on System Workbench

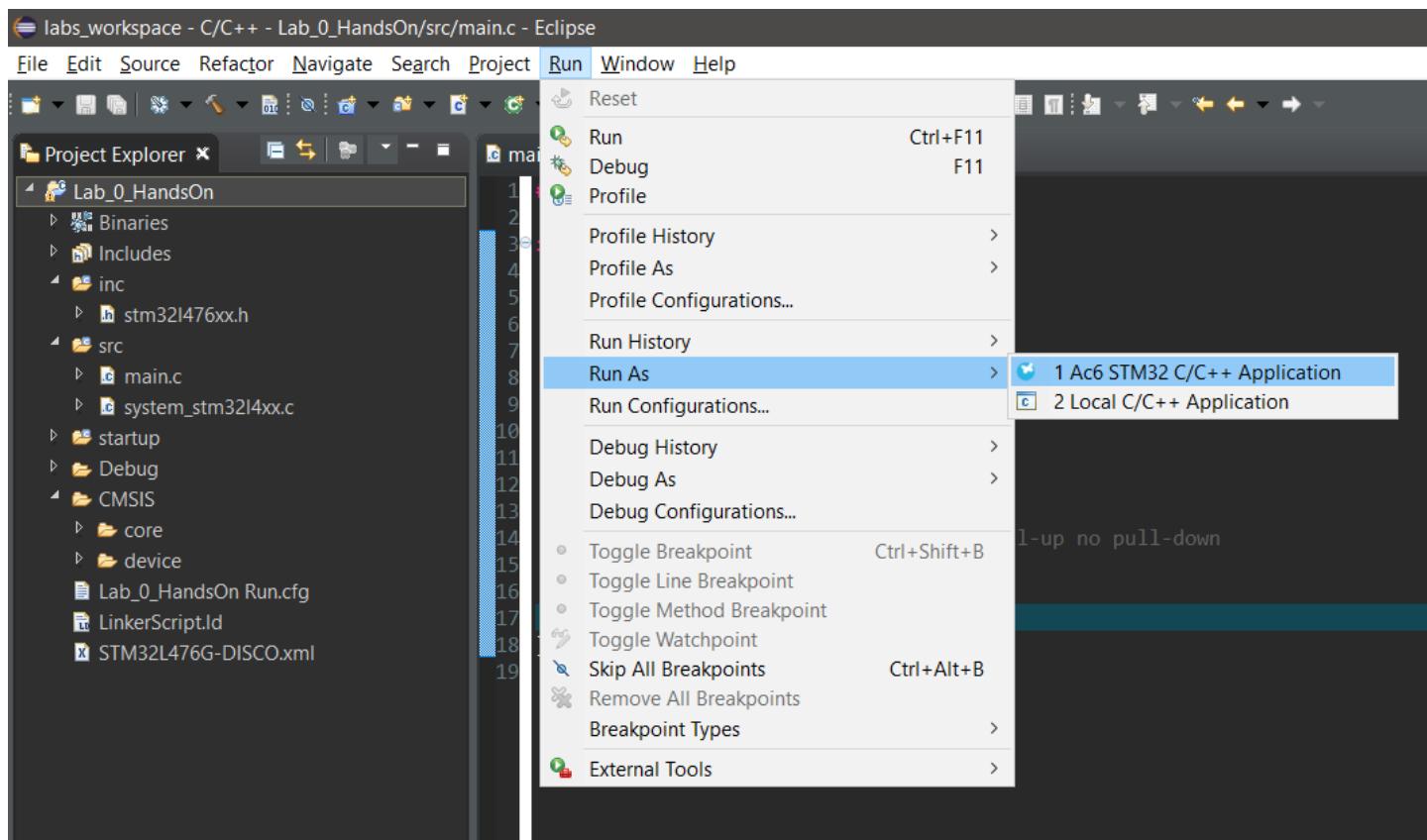
- After you're done writing your code, you will need to **compile** it, and **upload** it to the development kit.
 - To compile, go to **Project** → **Build Project**.



- If everything is correct with your code, you will see the message **Build Finished** and no errors in the **Console** window.

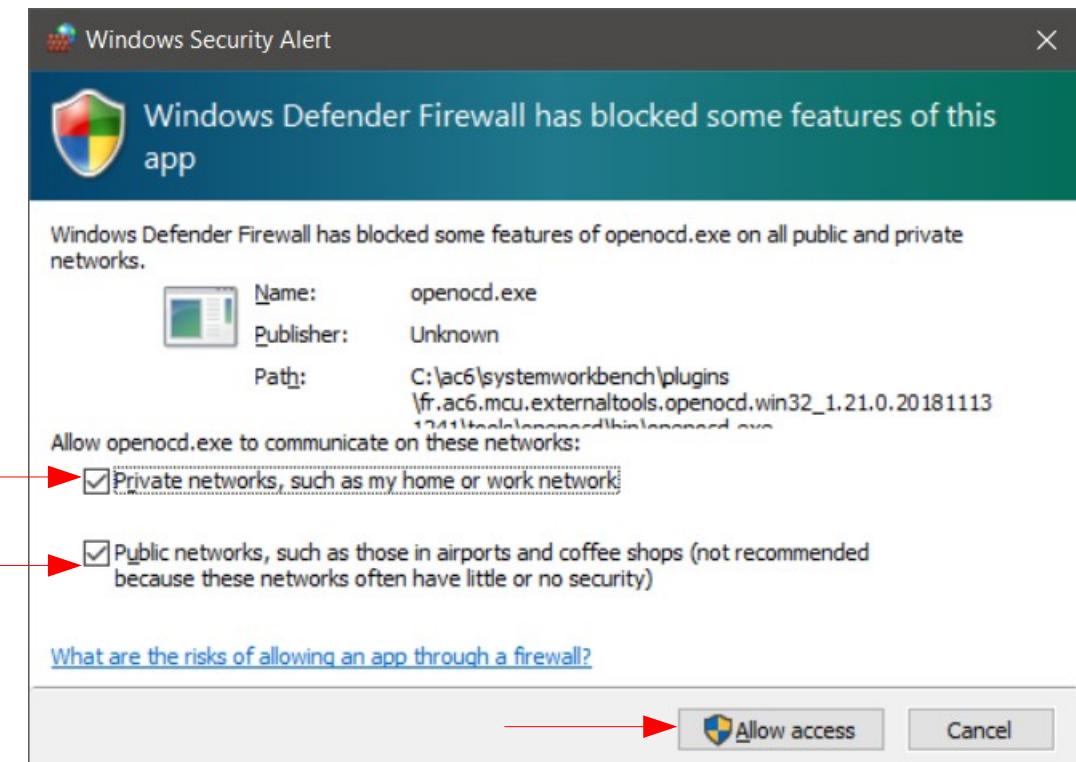
Uploading your code using System Workbench

- To upload your newly compiled code, go to **Run** → **Run As** → **Ac6 STM32 C/C++ Application**.
- This will upload your compiled code and reset the development kit.



Uploading your code using System Workbench

- When uploading, the application may ask for permission to use the network. Make sure you allow access.



Manually Programming and Debugging the Board



- The **debug** interface of most development boards, such as **STM32L4 Discovery Kit**, often provides a **USB mass storage interface**. When a board is connected to a computer, it is automatically mounted as a USB drive.
- To program the board, we only need to copy the generated **.bin** file to the mounted USB drive.

Manually Programming and Debugging the Board



- **OpenOCD (Open On-Chip Debugger)** is an open-source software that is widely used for debugging and downloading executables to microprocessors. **OpenOCD** runs as a server (also known as a **daemon**) on a host computer and serves two purposes:
 - It receives commands from either **Telnet** or **gdb** via TCP/IP connection.
 - It translates commands received to **JTAG/SW** commands, and sends them to the target ARM Cortex-M processor via the hardware debugger.

